

What is a Knowledge Graph?



Mikhail Galkin

Postdoc @ Mila & McGill

Outline

- On the definition & representation
- Part I: Symbolic
 - Logical Foundations
 - Databases & Querying
 - KG Construction
- Part II: Vector
 - NLP
 - KG Embeddings
 - Graph ML

On the definition of a Knowledge Graph

Given entities \mathcal{E} , relations \mathcal{R} , KG is a directed multi-relational graph \mathcal{G} that comprises triples (s, p, o)

$$\mathcal{G} \subseteq \mathcal{E} \times \mathcal{R} \times \mathcal{E}$$
$$(s, p, o) \in \mathcal{G}$$

- * describes entities and relations
- * defines a schema
- * interrelating arbitrary entities
- * various topical domains

“Abstract schema and instances”

“Every RDF / LPG / RDF* graph is a knowledge graph”

On the definition of a Knowledge Graph

Given entities \mathcal{E} , relations \mathcal{R} , KG is a directed multi-relational graph \mathcal{G} that comprises triples (s, p, o)

$$\mathcal{G} \subseteq \mathcal{E} \times \mathcal{R} \times \mathcal{E}$$
$$(s, p, o) \in \mathcal{G}$$

- * describes entities and relations
- * defines a schema
- * interrelating arbitrary entities
- * various topical domains

“Abstract schema and instances”

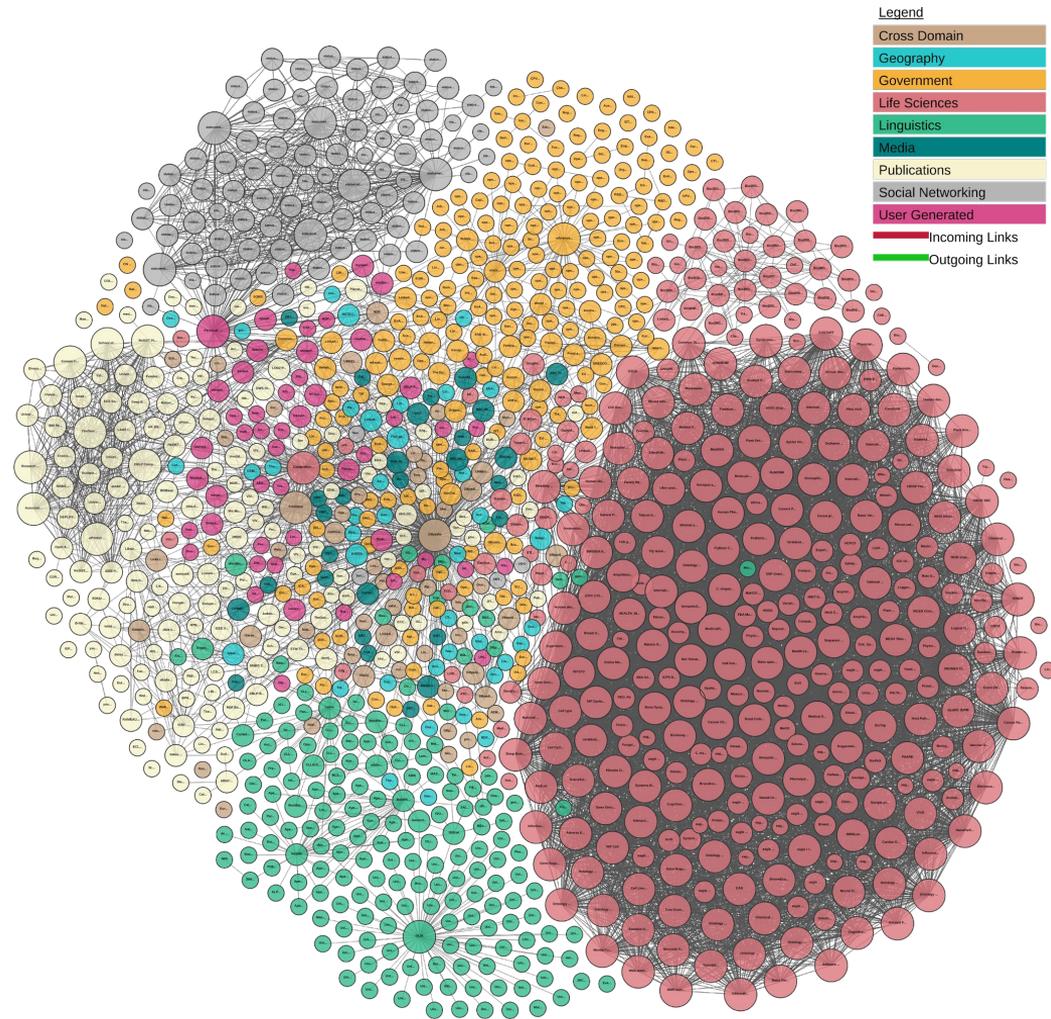
“Every RDF / LPG / RDF* graph is a knowledge graph”

Graph-structured world model

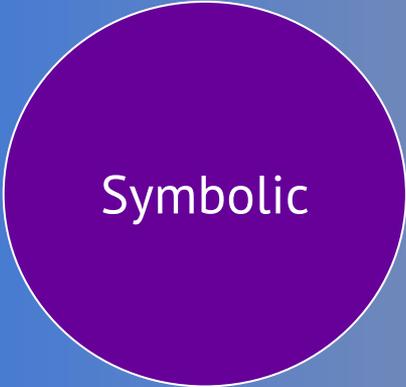
World models?

Entities and
relations define our
domain of discourse

How to encode it?



On representation of Knowledge Graphs



Symbolic

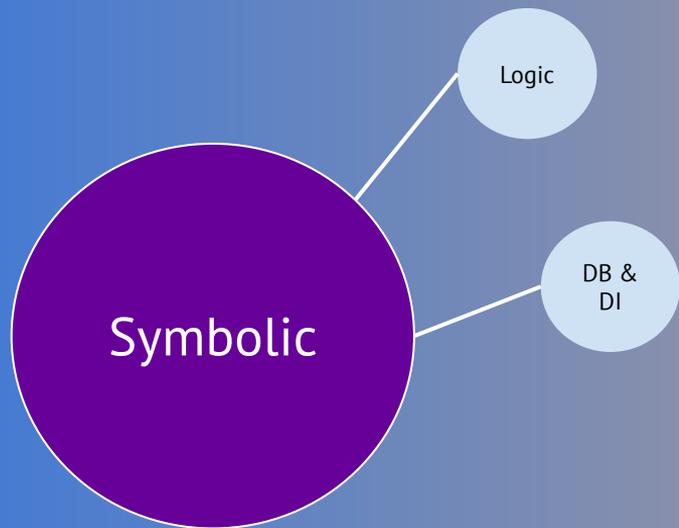
s, p, o
 $p(s, o)$
 (s, p, o)



Vector

$s, p, o \in \mathbb{R}^d$

On representation of Knowledge Graphs

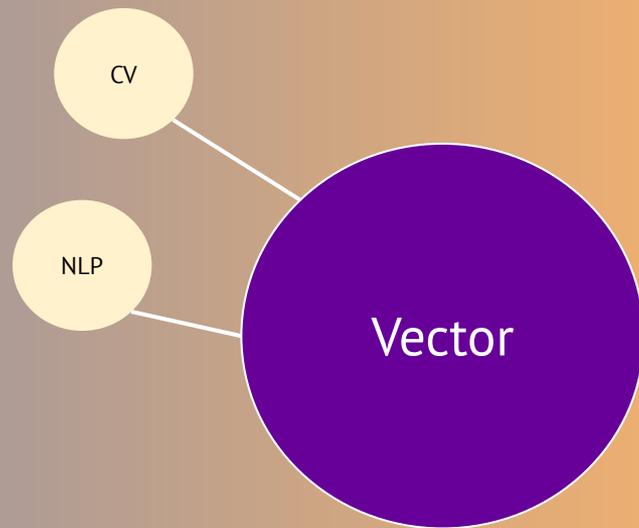


s, p, o
 $p(s, o)$
 (s, p, o)

Open-world assumption

Closed-world assumption

Temporal / evolving



$s, p, o \in \mathbb{R}^d$

Symbolic: Triples



RDJ
 RDJ
 Sherlock_Holmes
 Sherlock_Holmes

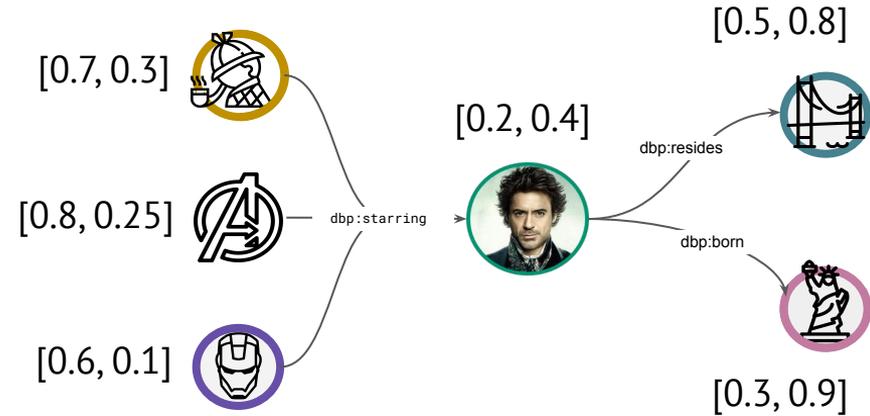
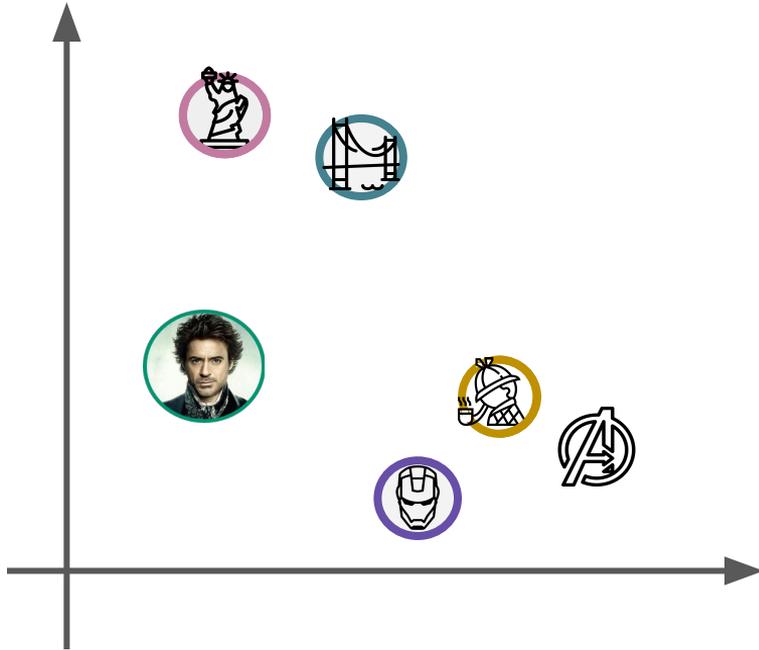
dbp:resides SF .
 dbp:born NY .
 dbp:studio WB .
 dbp:starring RDJ .

Avengers
 Avengers
 Iron_Man
 Iron_Man

dbp:studio Marvel .
 dbp:starring RDJ .
 dbp:studio Marvel .
 dbp:starring RDJ .

Vector: Embeddings

$$E \in \mathbb{R}^{N_e \times d}$$
$$R \in \mathbb{R}^{N_r \times d}$$



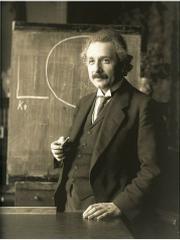
Part I: Symbolic

History



2007

Albert Einstein



Einstein in 1921, by Ferdinand Schmutzer

Born	14 March 1879 Ulm, Kingdom of Württemberg, German Empire
Died	18 April 1955 (aged 76) Princeton, New Jersey, U.S.
Citizenship	Kingdom of Württemberg, part of the German Empire (1879–1896) ^[note 1] Stateless (1896–1901) Switzerland (1901–1955) Austria, part of the Austro-Hungarian Empire (1911–1912) Kingdom of Prussia, part of the German Empire (1914–1918) ^[note 1] Free State of Prussia (Weimar Republic, 1918–1933)

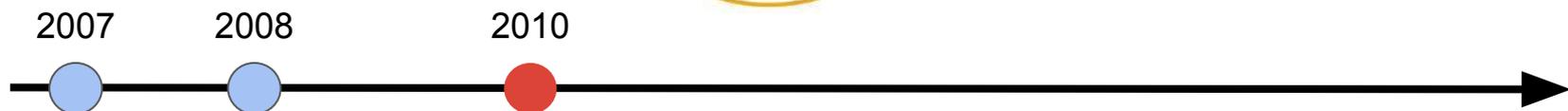
- Derived from parsing Wikipedia infoboxes
- 6B+ facts
- The first de-facto standard for creating and publishing KGs

History



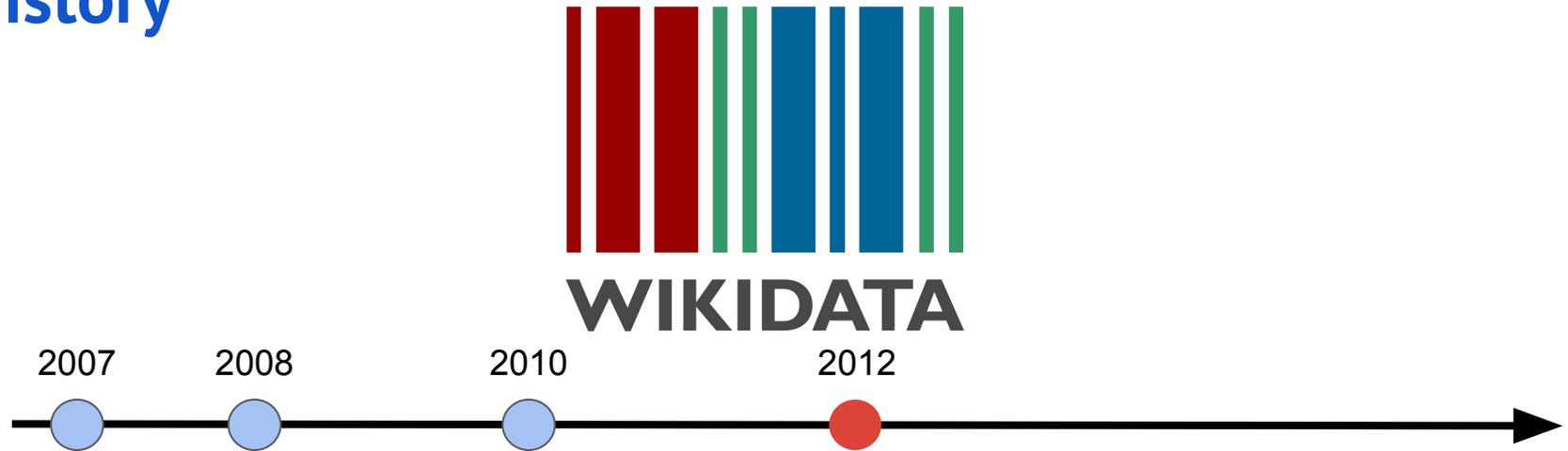
- Wikipedia + categories from WordNet
- 120M+ facts

History



- NELL - Never Ending Language Learner
- Automatic facts from parsing web pages
- 15B+ facts

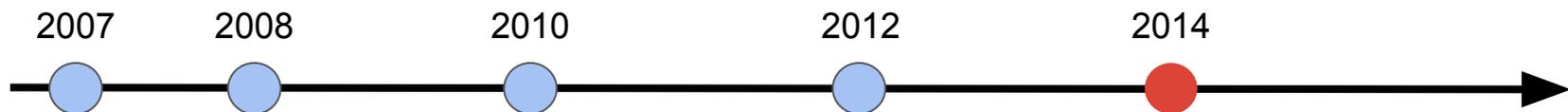
History



- The source of facts for Wiki infoboxes
- Flexible schema + qualifiers
- 100M+ entities, 7B+ statements
- Big Tech contributes to Wikidata

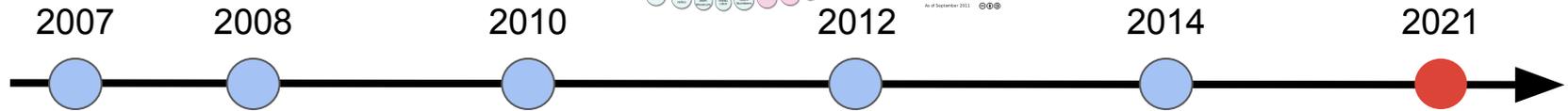
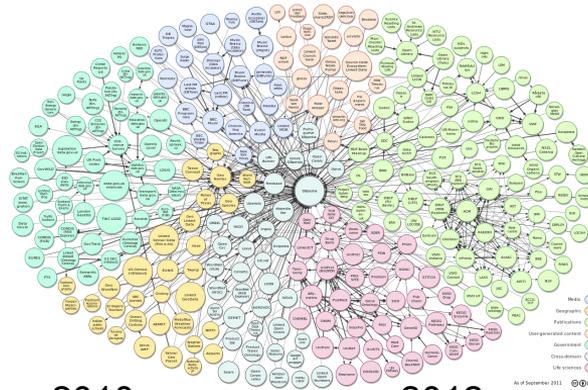
History

Google



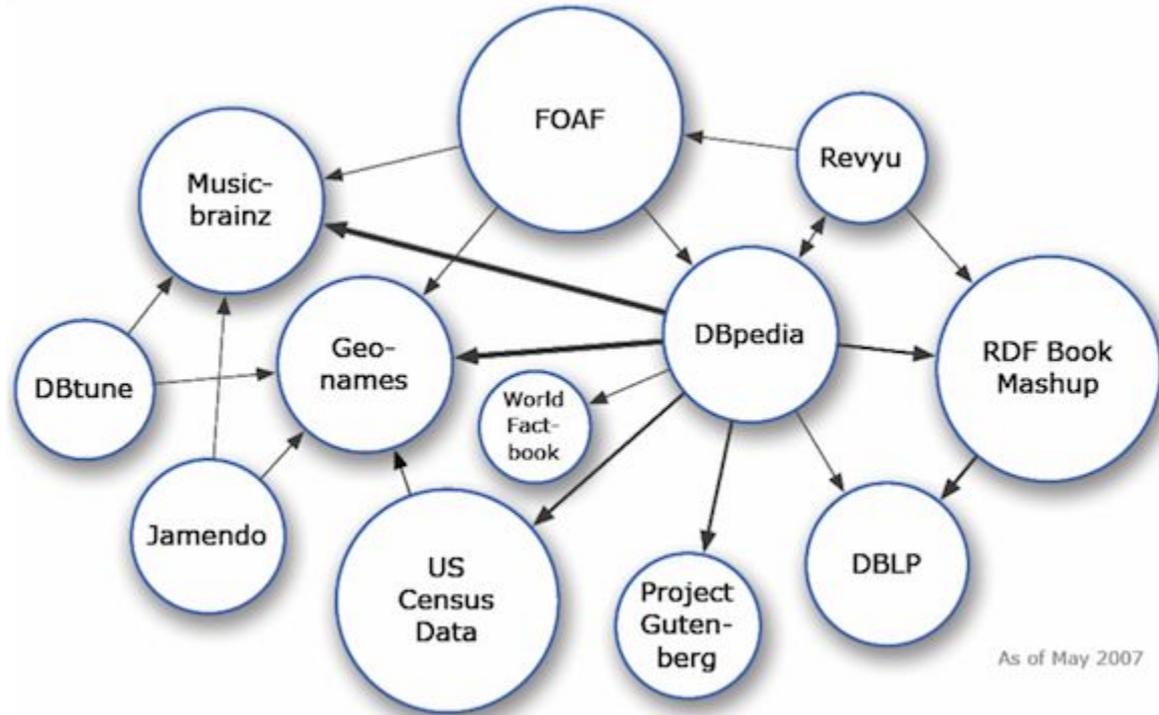
- Google Knowledge Graph - based on the acquired Freebase (2007)
- Common knowledge + user-specific info
- Everyone else started to want “my own KG” after that

History

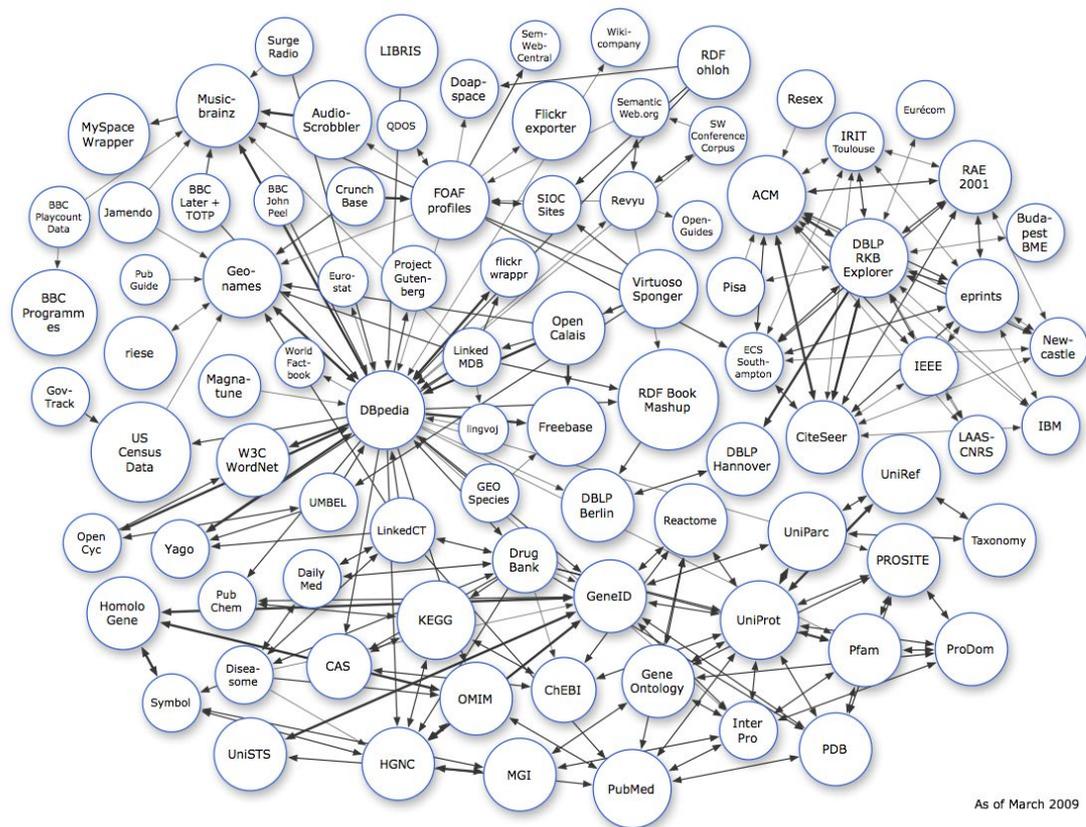


- Open and Linked KGs
- Domain-specific KGs in various domains
- Personal KGs
- ... many more

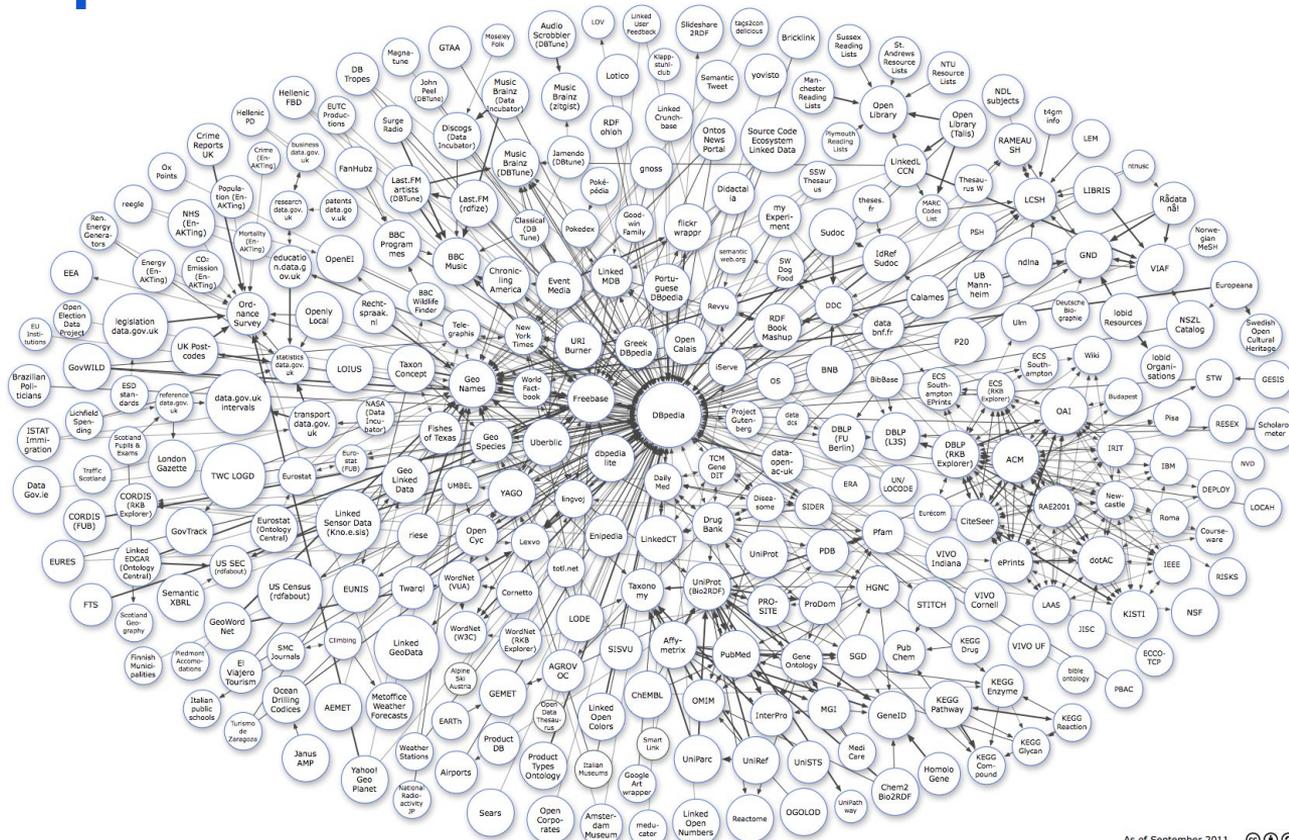
Linked Open Data - 2007



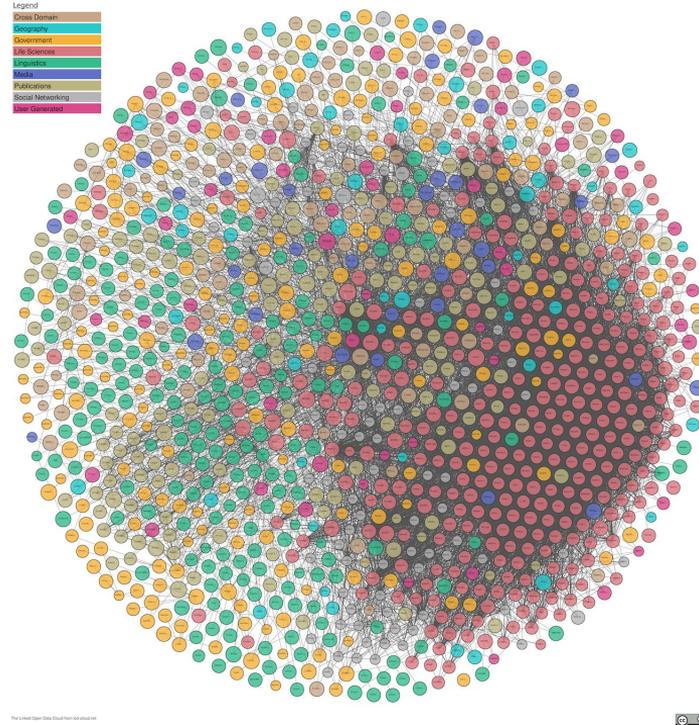
Linked Open Data - 2009



Linked Open Data - 2011



Linked Open Data - 2020



The Linked Open Data Cloud Project



Part I: Symbolic

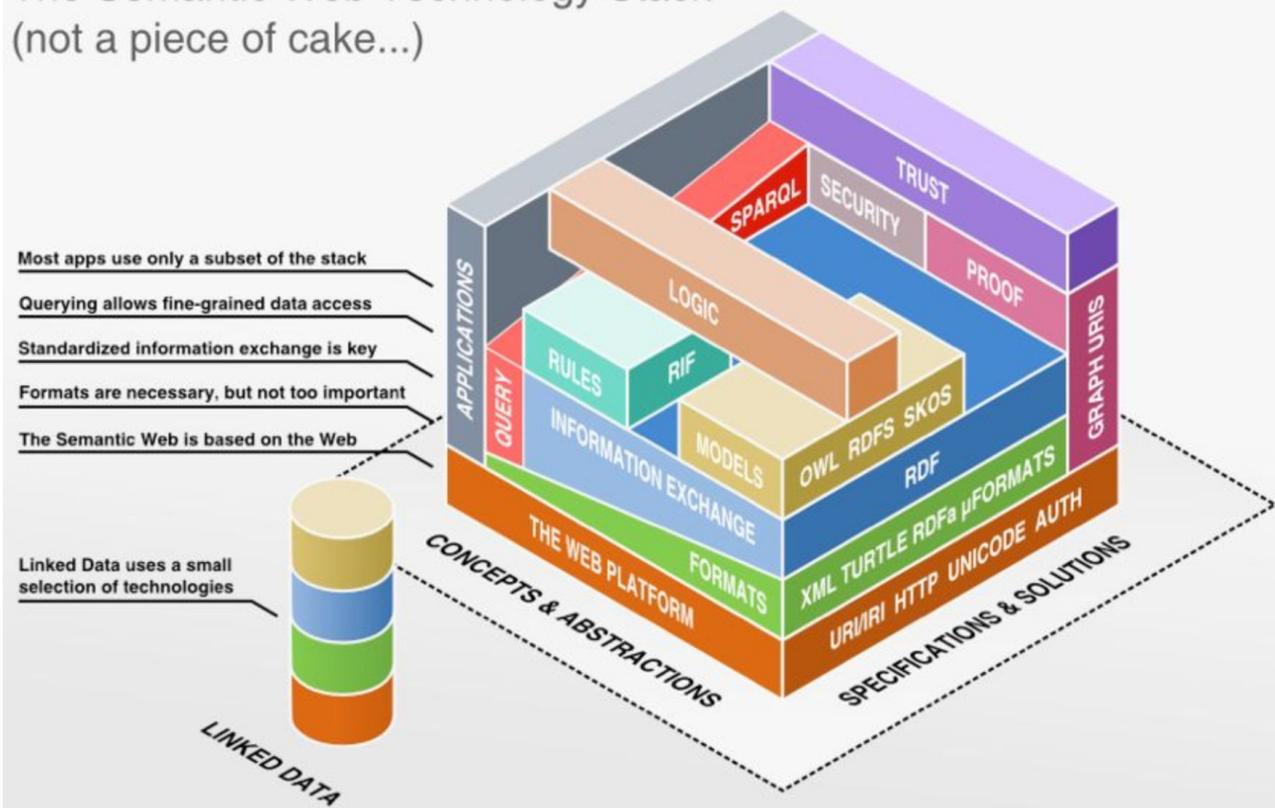
Logical Foundations

Semantic Web Layer Cake

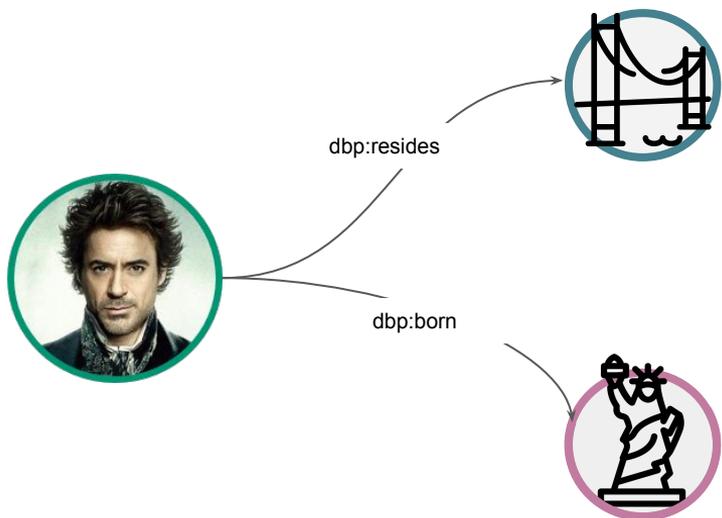
A stack of standards for KGs

1. Web Platform
2. Serialization
3. Modeling
4. Complex Logic
5. Querying
6. Interfaces

The Semantic Web Technology Stack
(not a piece of cake...)



Resource Description Framework (RDF)



1. Facts as triples
2. All entities and relations are (ideally) URIs

<http://example.com/RDJ>

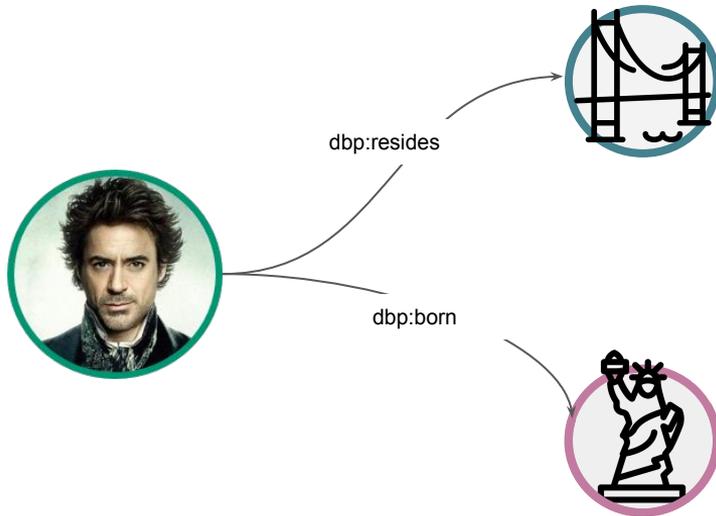
ex:RDJ

<http://dbpedia.org/resides> <http://dbpedia.org/resource/SanFrancisco>

dbp:resides

dbp:SanFrancisco

RDF + RDFS



ex:RDJ **rdf:type** ex:Person
ex:NewYork **rdf:type** ex:City

RDF + RDFS Class Hierarchies

RDFS Vocabulary

`rdfs:Class`

`rdf:Property`

`rdfs:range`

`rdfs:domain`

`rdfs:subClassOf`

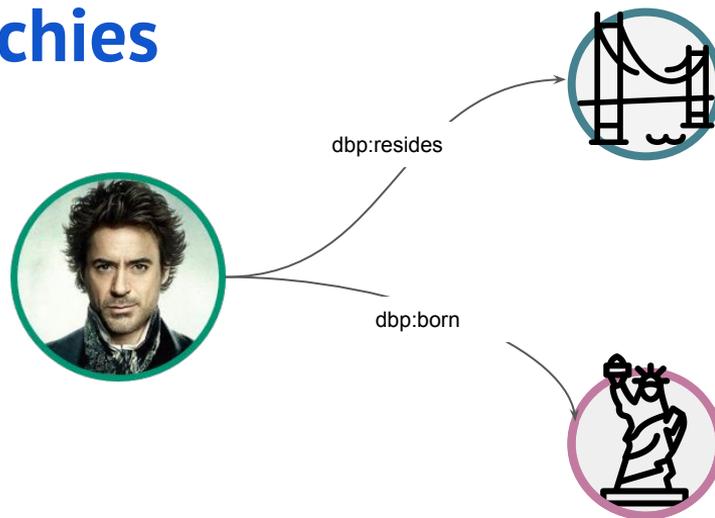
`rdfs:subPropertyOf`

`rdfs:label`

`rdfs:comment`

`rdfs:seeAlso`

`rdfs:isDefinedBy`



`ex:RDJ`

`ex:Actor`

`ex:Person`

`rdf:type`

`rdfs:subClassOf`

`rdfs:subClassOf`

`ex:Actor`

`ex:Person`

`ex:Mammal`

RDF + RDFS Property Ranges & Domains

RDFS Vocabulary

`rdfs:Class`

`rdf:Property`

`rdfs:range`

`rdfs:domain`

`rdfs:subClassOf`

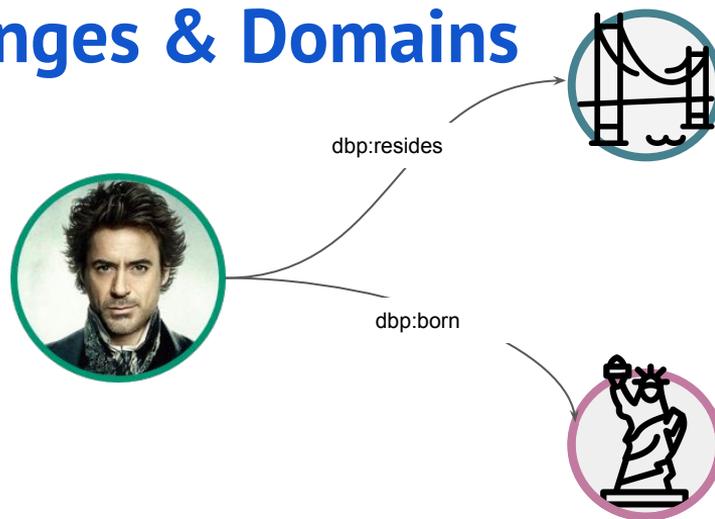
`rdfs:subPropertyOf`

`rdfs:label`

`rdfs:comment`

`rdfs:seeAlso`

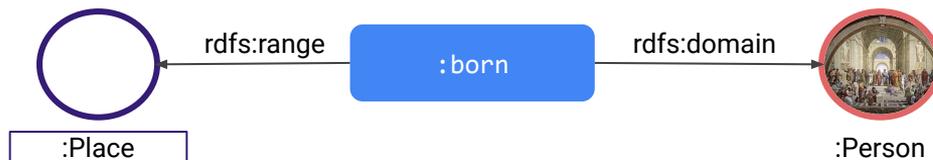
`rdfs:isDefinedBy`



`dbp:born`
`dbp:born`

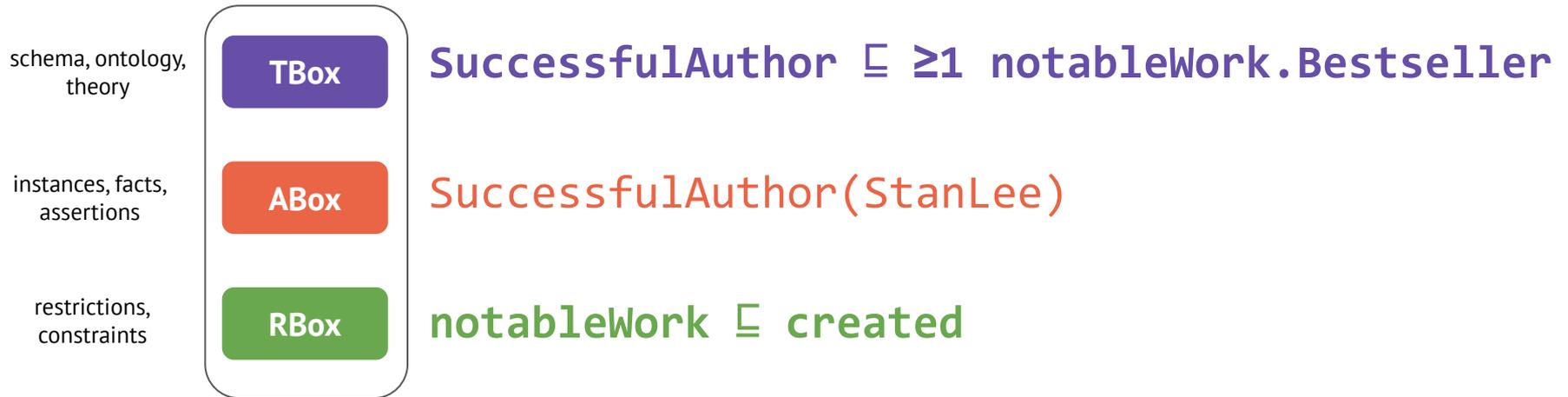
`rdfs:domain`
`rdfs:range`

`ex:Person`
`ex:Place`



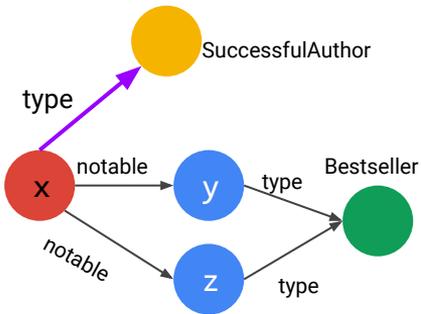
More Logics: OWL

Based on logical formalisms, e.g., Description Logics (DL)



Logically consistent collection of axioms

More Logics: OWL

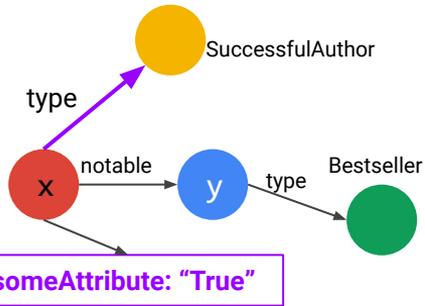


eg, Qualified Restrictions

`SuccessfulAuthor \sqsubseteq ≥ 1 notableWork.Bestseller`

```
:SuccessfulAuthor a owl:Class ;  
  rdfs:subClassOf [  
    a owl:Restriction;  
    owl:onProperty :notableWork;  
    owl:minQualifiedCardinality 1;  
    owl:onClass :Bestseller ] .
```

Reasoners



- Input: RDF/OWL graph
Output: RDF/OWL graph with new facts (assertions)
 - New node attributes
 - New edges between nodes
- Every fact can be explained (most ML models can't do that)
- Inference time grows very fast with graph size
- 🔥 research: speed of ML reasoning + explainability of rule-based

Explanation 1 Display laconic explanation

Explanation for: instanceB Type C

instanceB predicateA instanceA

?

instanceA Type A

?

C EquivalentTo predicateA some A

?

Knowledge Graph

TBox (Terminology Box)

Data schema

Ontology

Онтология:

- Formal model curated by experts
- Often created & maintained manually

ABox (Assertion Box)

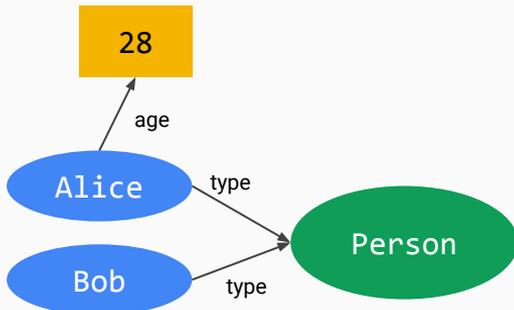
Actual “content”

Triples, edges between entities

- Often created from existing sources using **semantic data integration**

Open World Assumption

- Incomplete picture of the world
- Everything not explicitly stated - *possibly* true
- Extendable by design



Closed World Assumption

- Explicitly state everything about the world
- Everything not True == False
- Source of truth
 - Column in DB
 - Object field
 - Frame slot

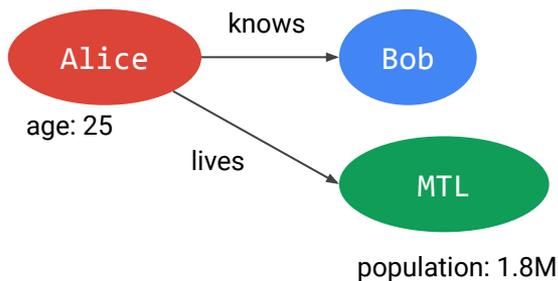
Person	Age
Alice	28
Bob	N/A

Part I: Symbolic

Graph Databases & Querying

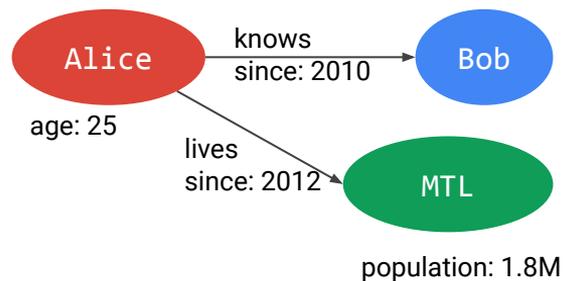
Graph DBs: RDF vs LPG

RDF



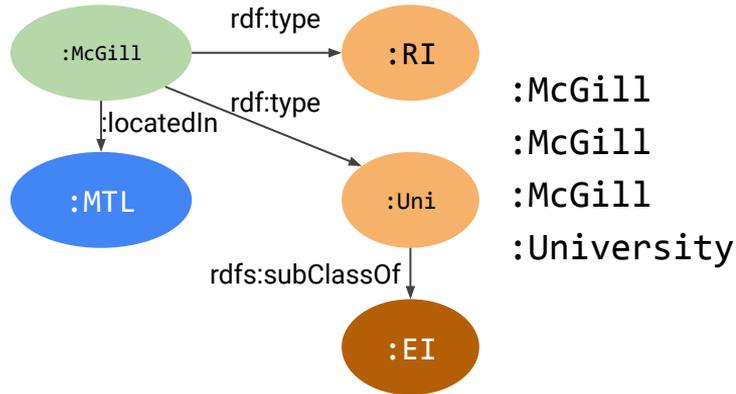
- Query Language: SPARQL
- RDFS/OWL properties of predicates
- Semantic scheme (w/ ontologies)
- Logical inference

LPG (Labeled Property Graph)



- Qs Cypher, Gremlin, GraphQL
- Any properties of predicates
- Non-semantic scheme
- No logical inference

SPARQL Query Structure



:McGill
:McGill
:McGill
:University

rdf:type
rdf:type
:locatedIn
rdfs:subClassOf

:University .
:Research_Institution .
:MTL .
:Educational_Institution .

SPARQL Query Structure

Prefixes

```
PREFIX rdf: <http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
```

```
PREFIX rdfs: <http://www.w3.org/2000/01/rdf-schema#> .
```

Query Type

```
SELECT ?type ?city
```

Projected Variables

```
FROM <named_graph>
```

Graph Source

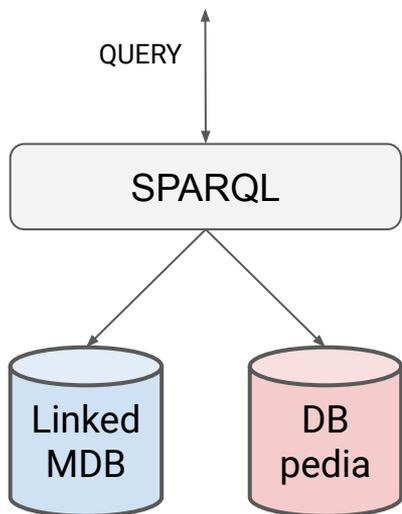
```
WHERE {  
  ?s    rdf:type          ?type .  
  ?s    :locatedIn      ?city .  
  ?type rdfs:subClassOf  ?num .  
}
```

BGP

Modifiers

```
ORDER BY <> LIMIT <num> OFFSET <num>
```

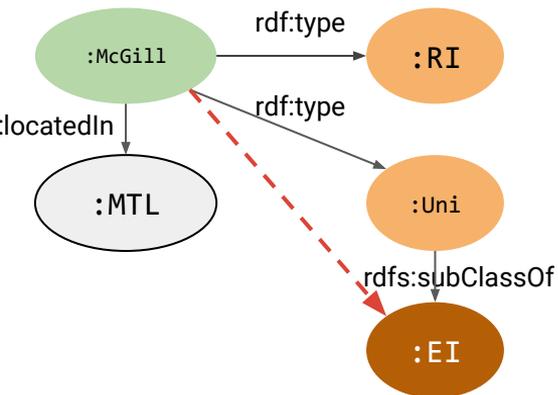
SPARQL 1.1 - Federated Querying



- Federated queries - query other endpoints within a query using **SERVICE**

```
SELECT ?film ?label ?subject WHERE {  
  SERVICE <http://data.linkedmdb.org/sparql> {  
    ?movie rdf:type movie:film .  
    ?movie rdfs:label ?label .  
    ?movie owl:sameAs ?dbpediaLink  
    FILTER (regex(str(?dbpediaLink), "dbpedia"))  
  }  
  SERVICE <http://dbpedia.org/sparql> {  
    ?dbpediaLink dct:subject ?subject .  
  }  
}
```

Advanced SPARQL - Reasoning



```
:McGill rdf:type
```

```
:McGill rdf:type
```

```
:McGill :locatedIn
```

```
:University rdfs:subClassOf :Educational_Institution .
```

```
(:McGill rdf:type
```

```
:University .
```

```
:Research_Institution .
```

```
:MTL .
```

```
:Educational_Institution .)
```

```
SELECT ?t WHERE {
  :McGill a ?t }
```

- Standard SPARQL - no reasoning, all triples have to be **materialized**
- Some Graph DBMS do allow for reasoning (inferring new triples in memory)
 - RDFS (subClassOf, range, domain)
 - OWL 2 RL / QL
 - SWRL
 - owl:sameAs



HOW TO STORE RDF DATA ?

- Native (NoSQL) vs Non-native (SQL)
- RDF vs LPG

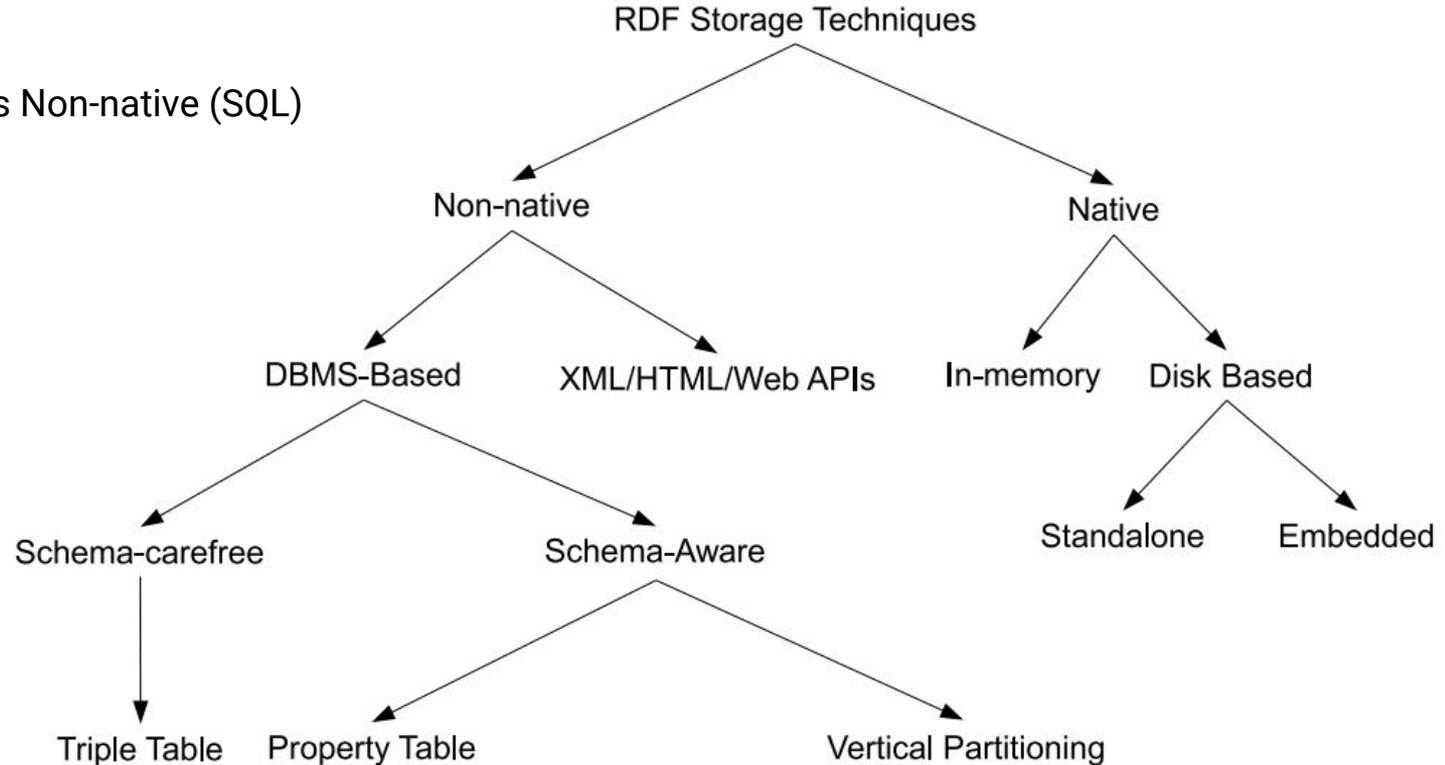
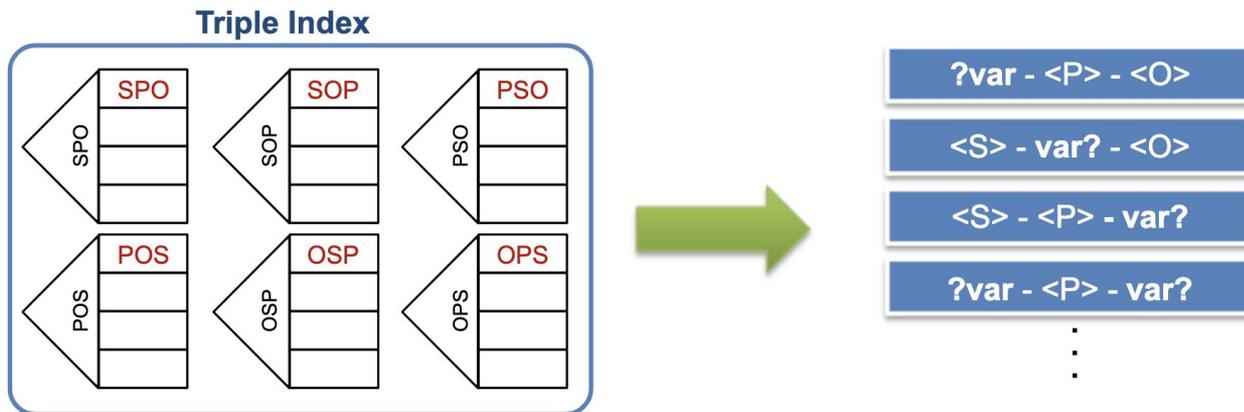


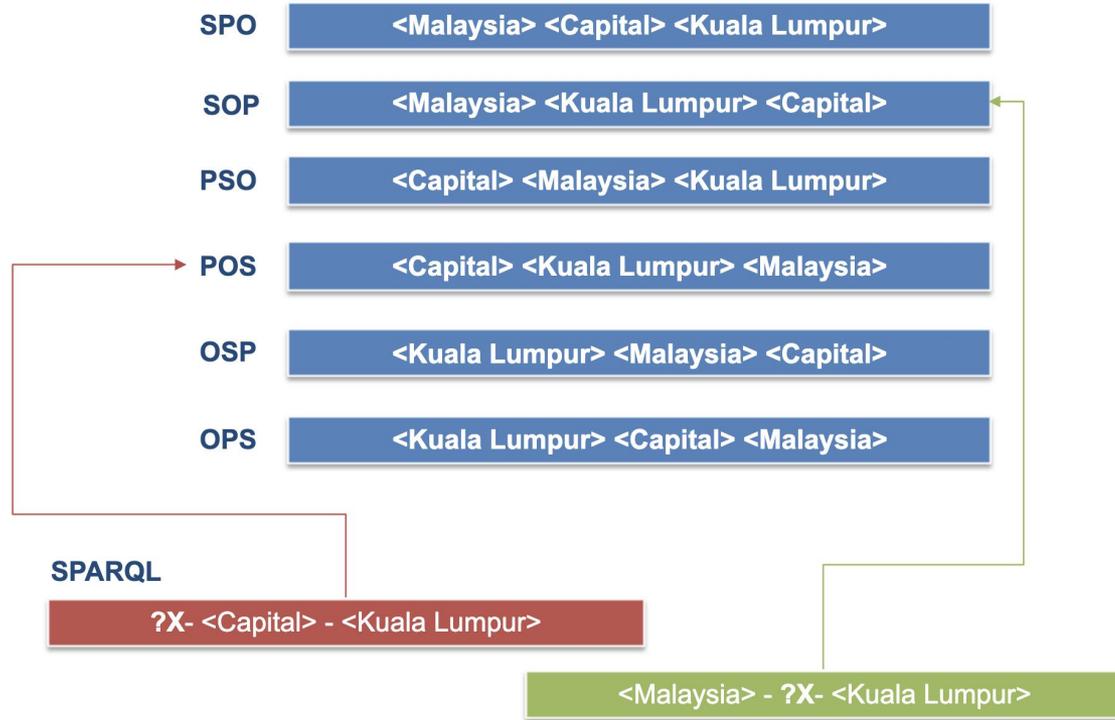
Figure 2. A classification of RDF data storage approaches

RDF Databases - Native - B+ Trees - RDF-3X

- Six separate indexes
 - (SPO, SOP, OSP, OPS, PSO, POS)
 - Stored in the leaf pages of the clustered B+ tree



RDF Databases - Native - B+ Trees - RDF-3X



RDF Databases - Native - B+ Trees - RDF-3X

- Store collation order
 - Neighboring indexes are very similar
 - Stores the change between triples

S	P	O
0	1	2
0	1	3
0	1	5

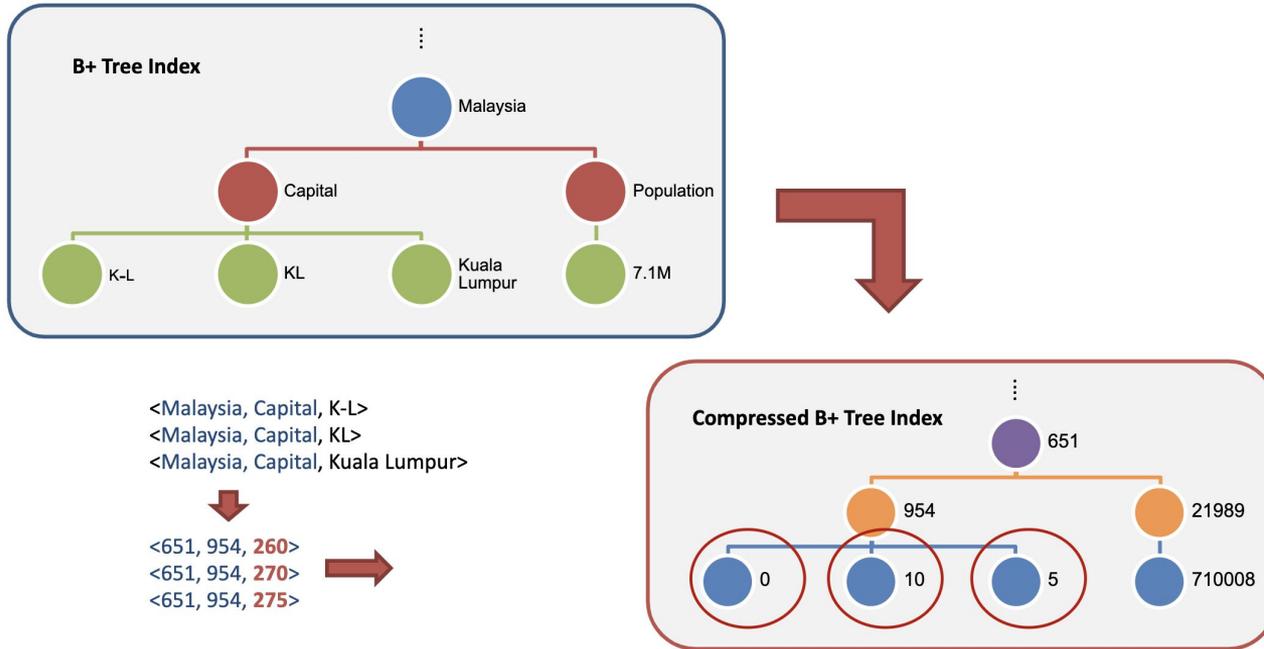


Compression using LZ77

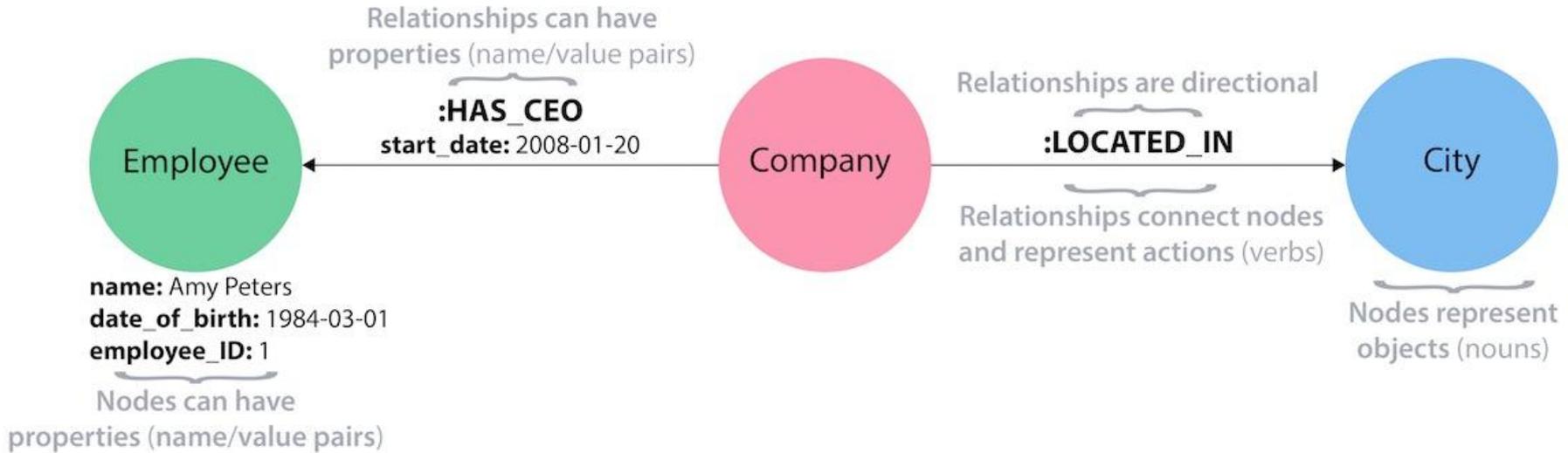
S	P	O
0	1	$(2-2) = 0$
		$(3-2) = 1$
		$(5-3) = 2$

RDF Databases - Native - B+ Trees - RDF-3X

- Compression
 - Stores only the change (δ) between triples



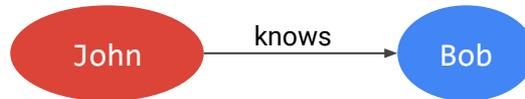
Labeled Property Graph (LPG) Databases



LPG - Cypher

- Standard for Neo4j
- Almost 1-1 mapping to SPARQL

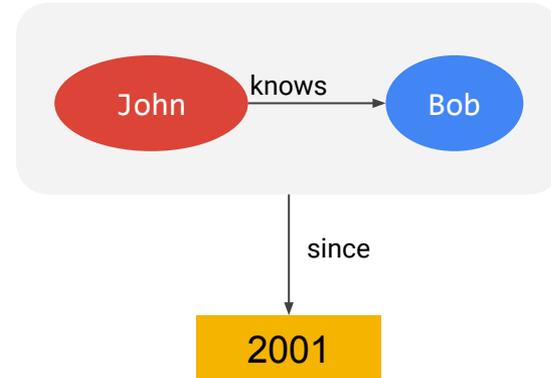
Cypher	SPARQL
<pre>MATCH (s:Person) WHERE s.name = "John" RETURN s;</pre>	<pre>SELECT ?s WHERE { ?s a :Person; :name "John" }</pre>
<pre>MATCH (s:Person)-[:knows]-(friend) WHERE s.name = "John" RETURN s, friend ;</pre>	<pre>SELECT ?s ?friend WHERE { ?s a :Person; :name "John" ; :knows ?friend }</pre>



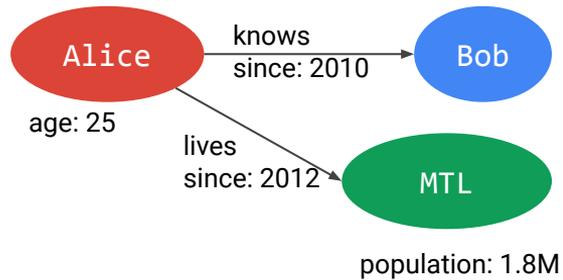
LPG - Cypher

- Standard for Neo4j
- **Almost** 1-1 mapping to SPARQL

Cypher	SPARQL* (Reification)
<pre>MATCH (s:Person)-[:knows {since:2001}] -> (js) RETURN s;</pre>	<pre>SELECT ?s WHERE { <<?s :knows :js>> :since 2001 }</pre>



RDF* / SPARQL*



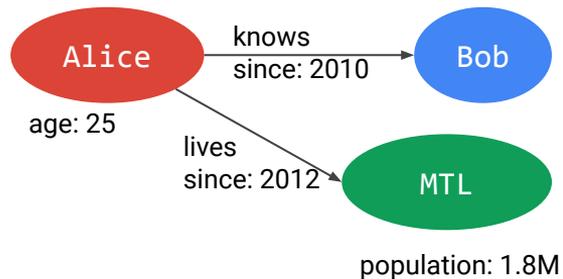
<< Alice knows Bob >> since 2010 .

<< Alice lives MTL >> since 2012 .

Alice age 25 .

MTL population 1.8M .

RDF* / SPARQL*



```
<< Alice knows Bob >> since 2010 .
```

```
<< Alice lives MTL >> since 2012 .
```

```
Alice age 25 .
```

```
MTL population 1.8M .
```

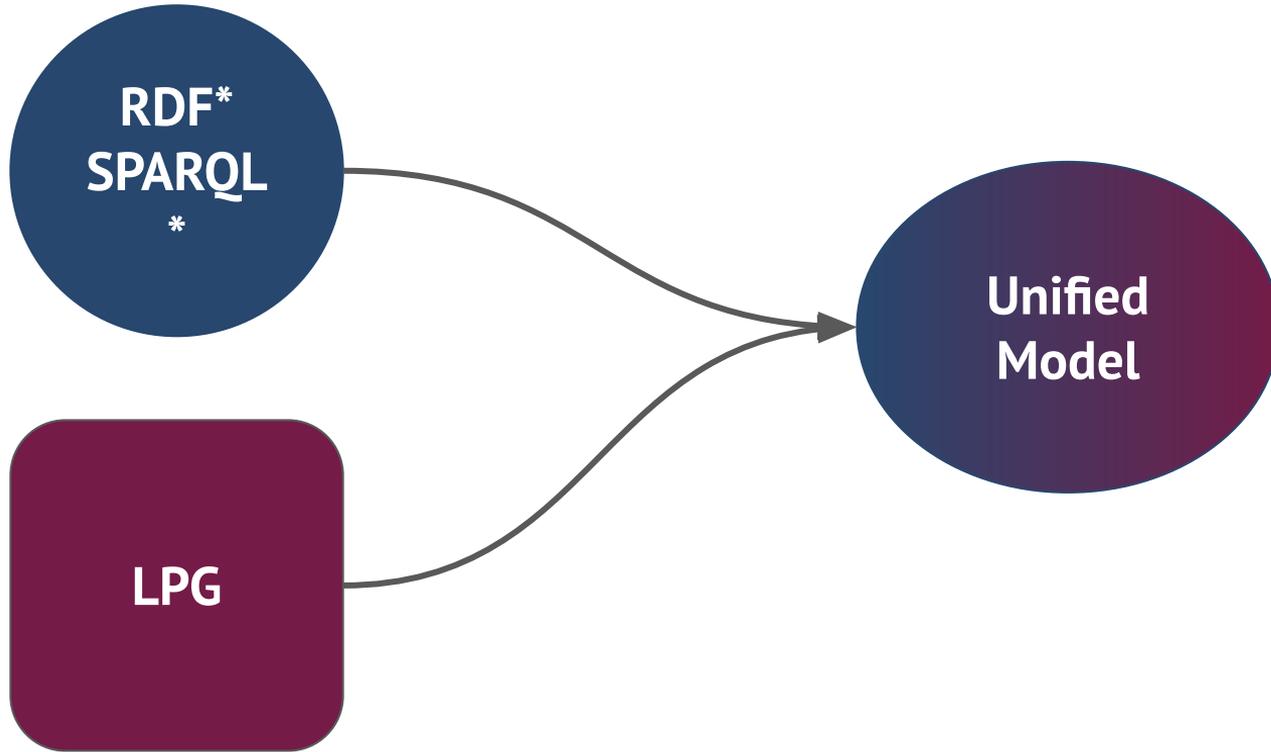
Since when Alice knows Bob?

```
SELECT ?date WHERE {  
  << Alice knows Bob >> since ?date . }
```

What is a population of a city when Alice lives since 2012?

```
SELECT ?population WHERE {  
  << Alice lives ?city >> since 2012 .  
  ?city population ?population . }
```

RDF* / SPARQL* + LPG Convergence



Part I: Symbolic

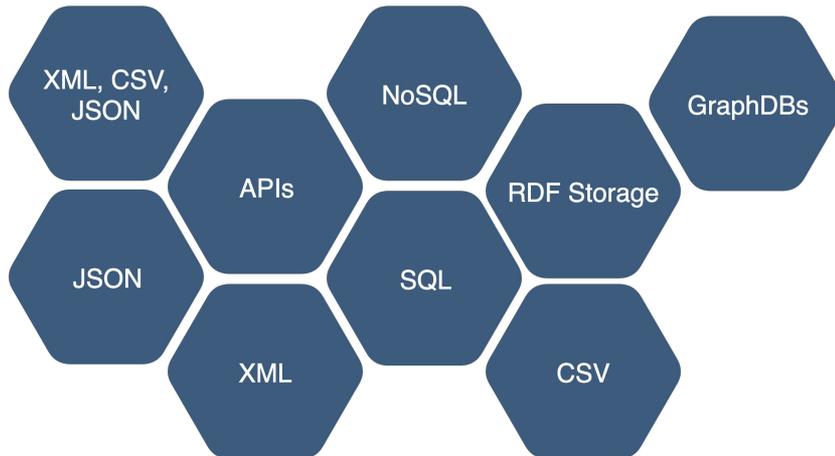
KG Construction

KG Construction

Knowledge Graph

Semantic Data Integration

Structured Sources

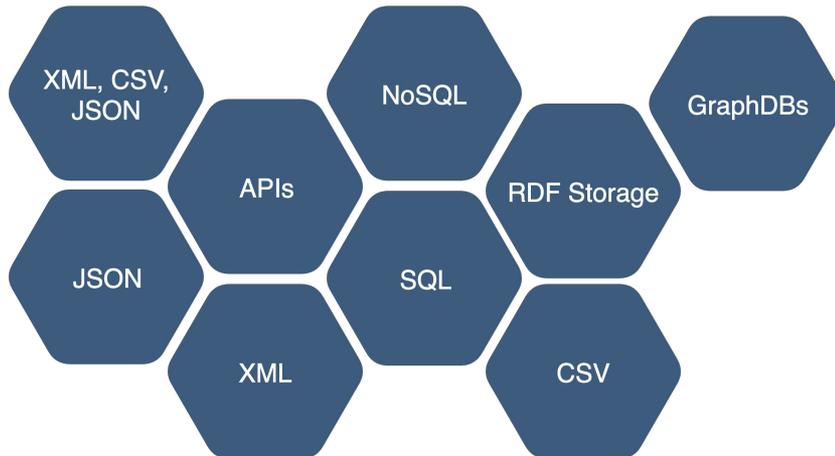


KG Construction

Knowledge Graph

Semantic Data Integration

Structured Sources



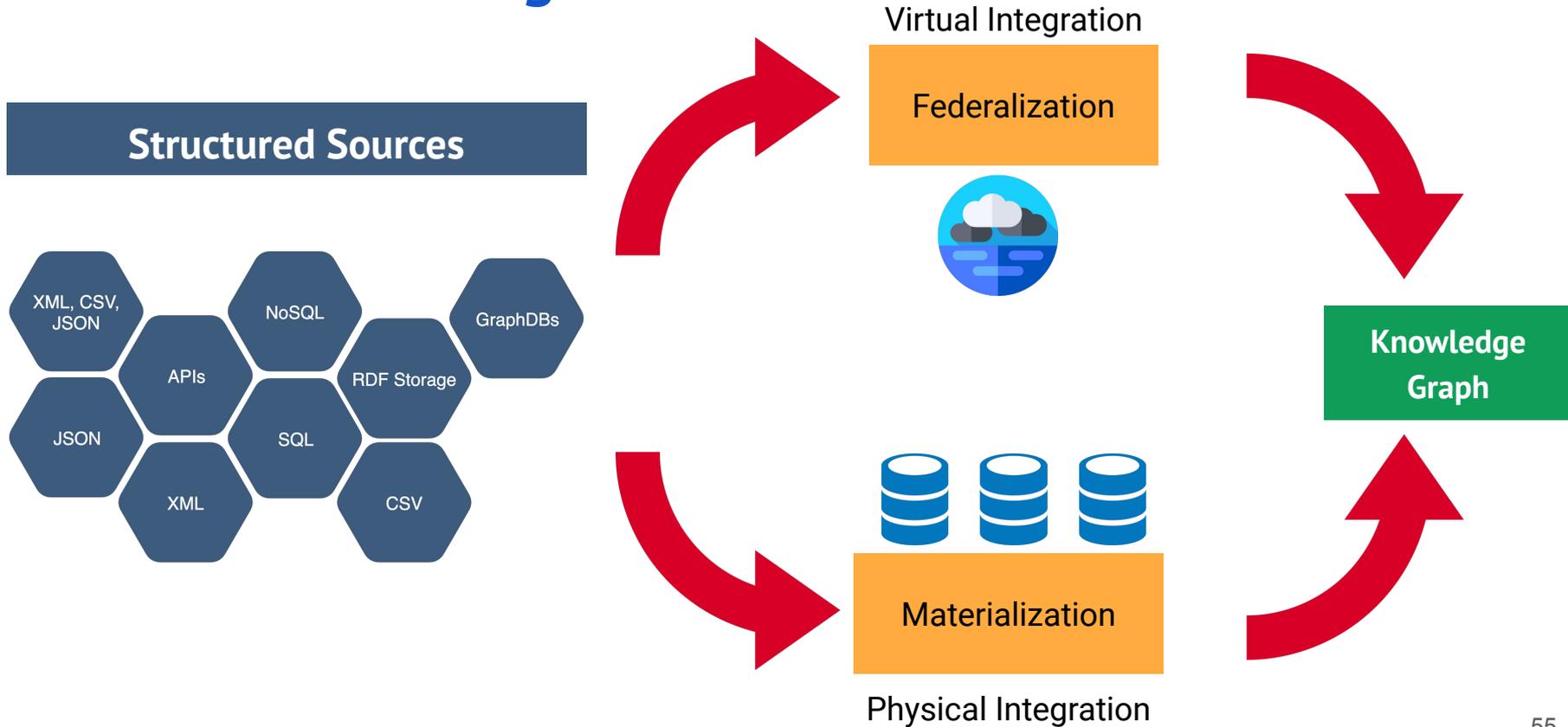
Knowledge Graph

Information Retrieval & NLP

Unstructured Sources



Semantic Data Integration

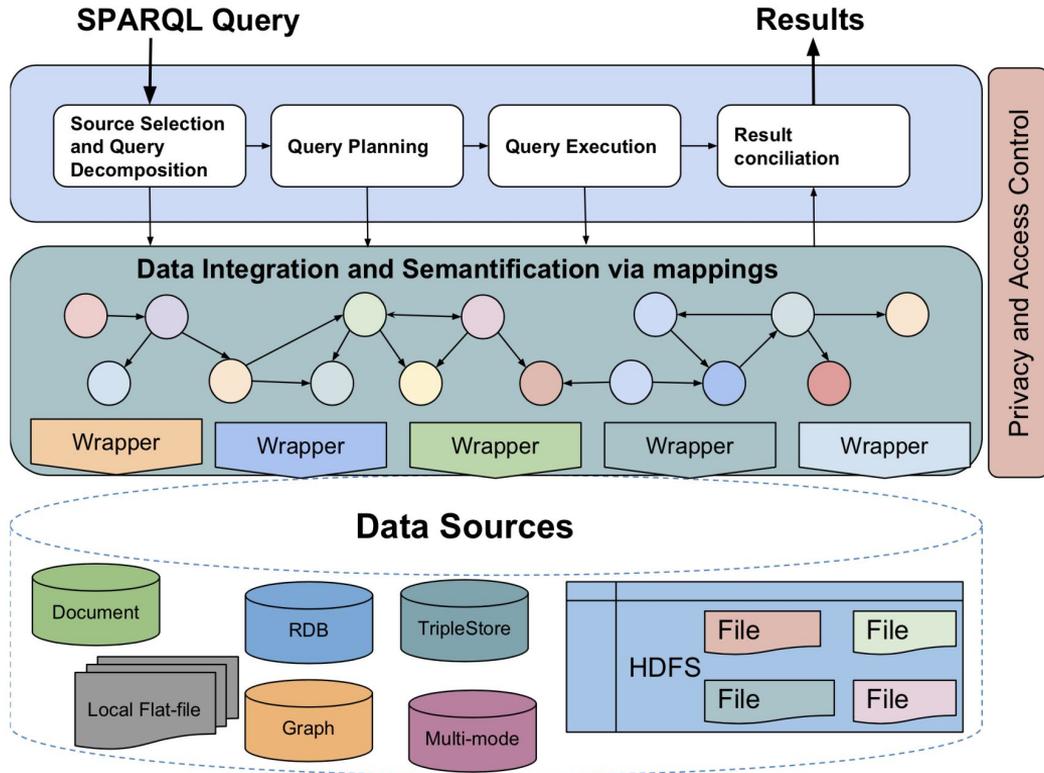


Physical Integration (Materialization)

Data Warehouses



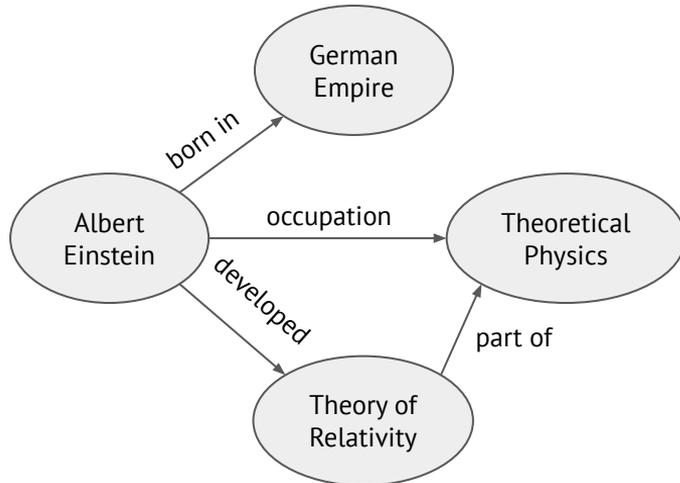
Virtual Integration (Federalization)



Data Lakes

Building KGs from texts

Albert Einstein was a German-born theoretical physicist who developed the theory of relativity.



Knowledge Graph

Information Retrieval

Unstructured Sources



Part II: Vector (some ML)

NLP

NLP - Named Entity Recognition

apple (Q89)

fruit of the apple tree
apples

Apple (Q1754545)

1990 album by Mother Love bone

Apple (Q213710)

UK international record label; imprint of Apple Corps Ltd.
LC 01074 | LC 1074 | Apple Records

Apple Inc. (Q312)

American producer of hardware, software, and services, based in Cupertino, California
Apple Computer, Inc. | Apple Computer | Apple Computer Inc | Apple | Apple Incorporated | Apple Computer Incorporated | 🍏



Who is the CEO of **Apple**?



Apple belongs to which genus?

movie character



Downey played **Iron Man** in which year?

Who is the alter ego of **Iron man**?

comic character

NLP - Relation Linking

Relations in a Knowledge Graph

List of known relations

Surface forms (synonyms),
easily multi-lingual

Relations constraints

Relations hierarchy

Most used types of
subjects and objects

Name all the movies in which Robert Downey Jr ^{wdt:P161} **acted**?

Find me all the films **casting** Robert Downey Jr ?

List all the movies **starring** Robert Downey Junior?

RDJ **has acted** in which movies?

cast member (P161)

actor in the subject production |

starring | film starring | actor | actress | contestant or a play

performer (P175)

actor, musician, band or other performer associated with this role or musical work

artist | musician | played by | portrayed by | recorded by | recording by | dancer | actor | musical artist

NLP - Question Answering

All
marvel
movies

Every
thing
starring
RDJ

How many **Marvel** **movies** was **Robert Downey Jr.**
casted in?

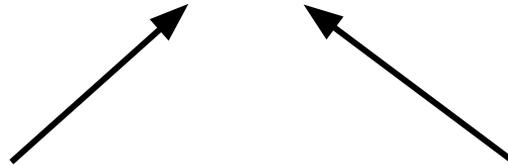
```
SELECT COUNT(?uri) WHERE {  
  ?uri dbp:studio dbr:Marvel_Studios.  
  ?uri dbo:starring dbr:Robert_Downey_Jr  
}
```

Find the
intersection

Count the
entities
left

NLP - Language Modeling

Robert Downey Jr. portrayed [MASK] in the Marvel movie in 2008.



Knowledge Graph

(Iron Man, cast member, Robert Downey Jr)
(Iron Man, production company, Marvel)
(Iron Man, released, 2008)
(Robert Downey Jr, character role, Tony Stark)
(Tony Stark, pseudonym, Iron Man)

Precise facts

Entities &
relations

Explainability

Unstructured Sources



Large-scale text corpora
(Wikipedia, OpenBooks, Reddit,
CommonCrawl, etc)

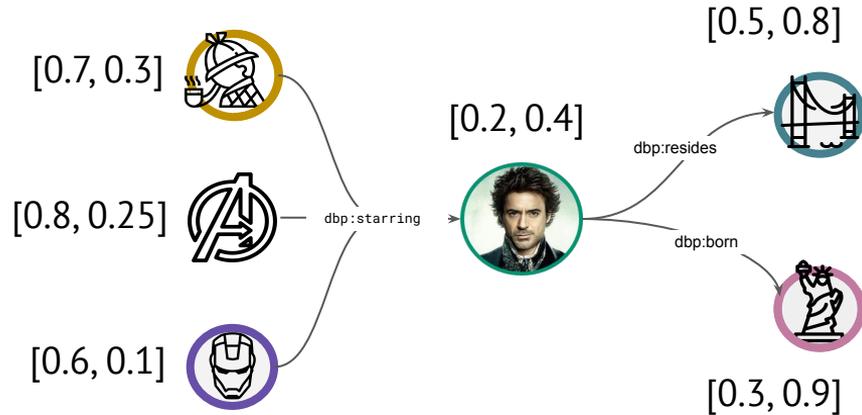
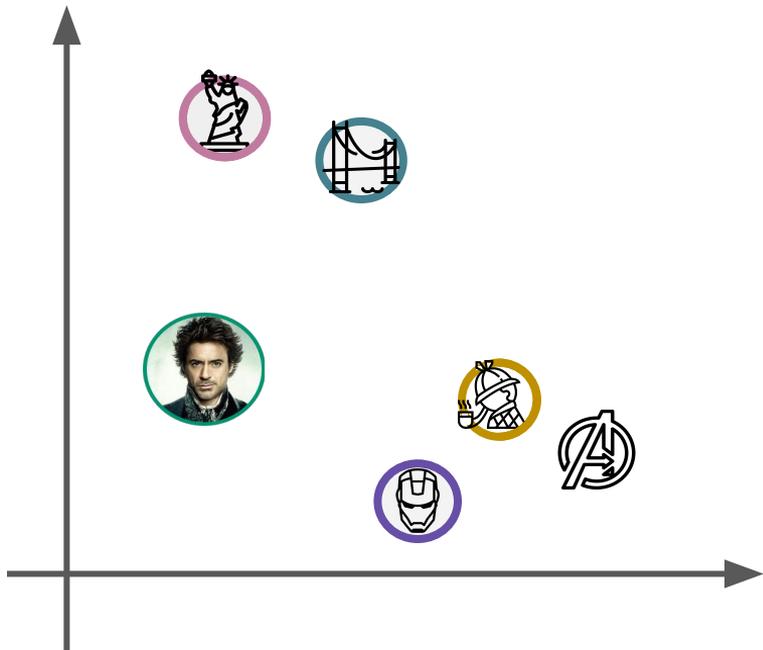
Part II: Vector (some ML)

Representation Learning (KG Embeddings)

Embeddings

$$E \in \mathbb{R}^{N_e \times d}$$

$$R \in \mathbb{R}^{N_r \times d}$$



Embeddings

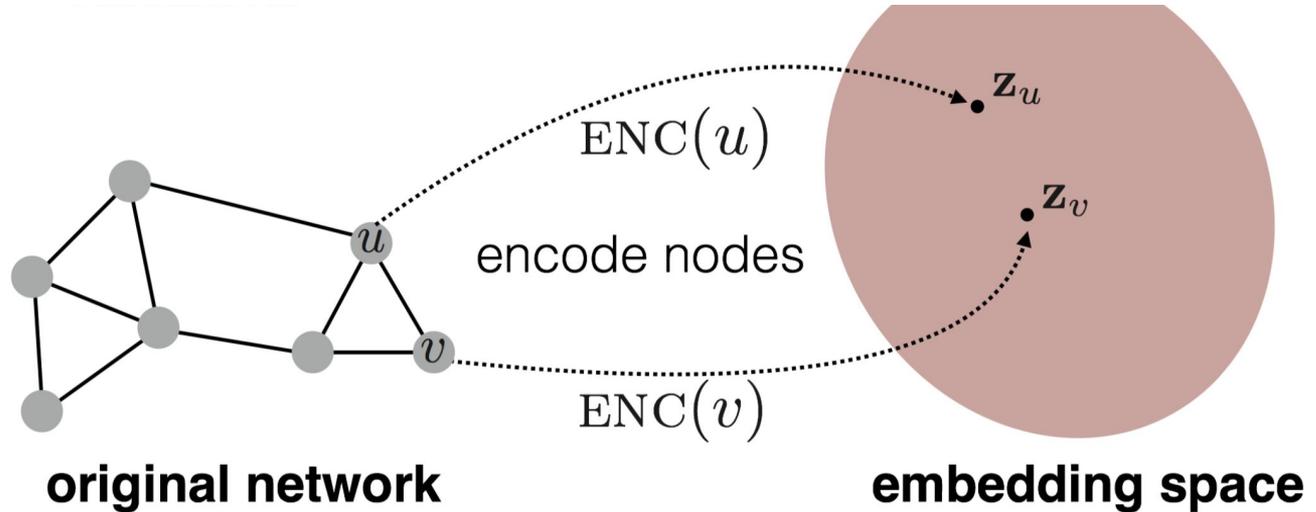
Tensor
Factorization

Goal: encode nodes so that **similarity in the embedding space (e.g., dot product)** approximates **similarity in the original network**

Translation

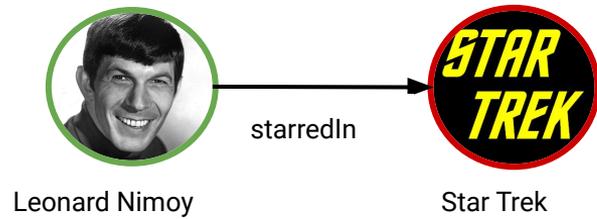
Neural Networks

Graph Neural
Nets

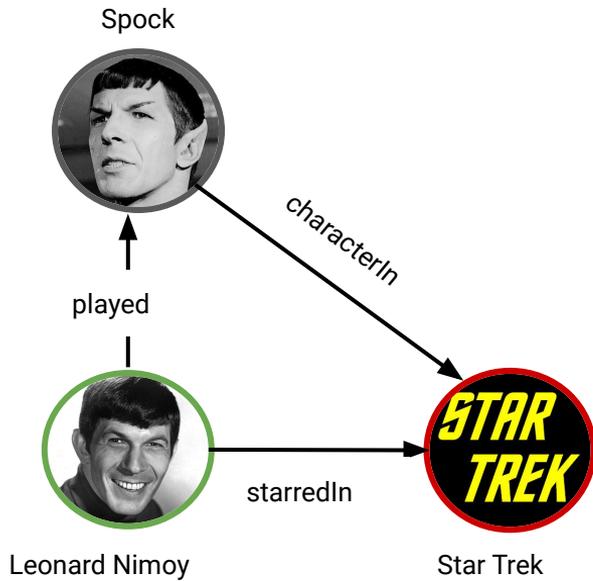


Source: Stanford CS224w, <http://web.stanford.edu/class/cs224w/>

KGE - Graphs as Tensors



KGE - Graphs as Tensors



			
	0	1	0
	0	0	0

starredIn

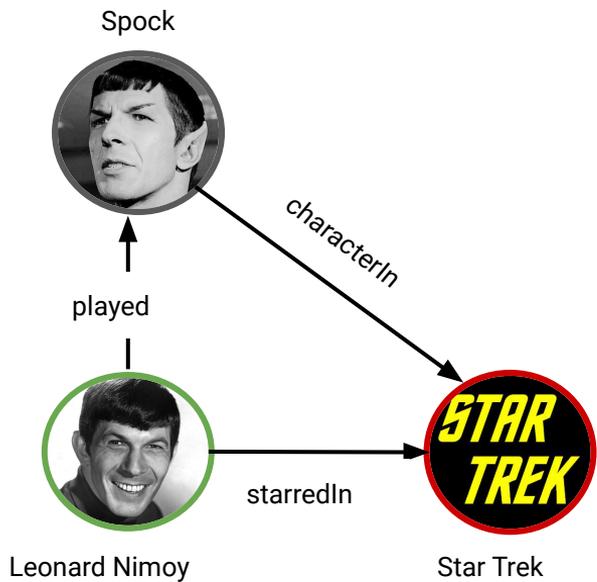
			
	0	0	1
	0	0	0

played

			
	0	0	0
	0	1	0

characterIn

KGE - Graphs as Tensors



	0	1	0
	0	0	0

starredIn

	0	0	1
	0	0	0

played

	0	0	0
	0	1	0

characterIn

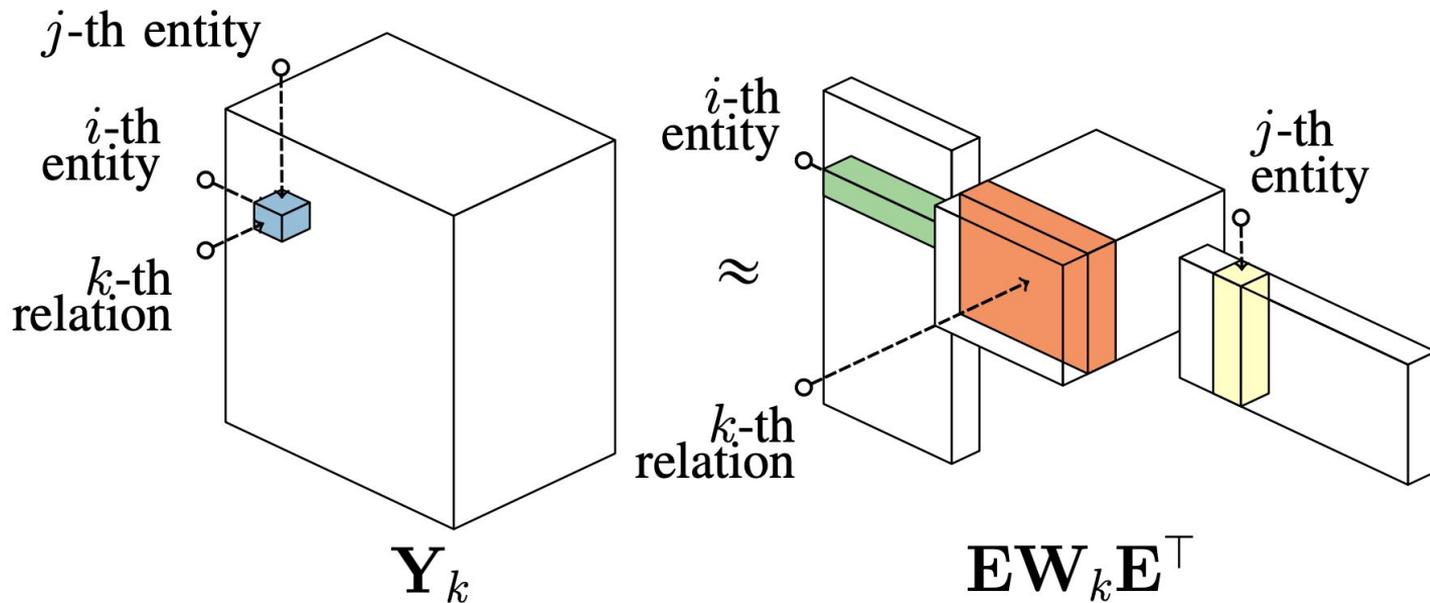
		0	0	0
	0	0	1	0
	0	1	0	0
	0	0	0	0
	0	0	0	0

$$\mathcal{T} : \mathbb{R}^{|E| \times |E| \times |R|}$$

KGE - RESCAL

Tensor Factorization

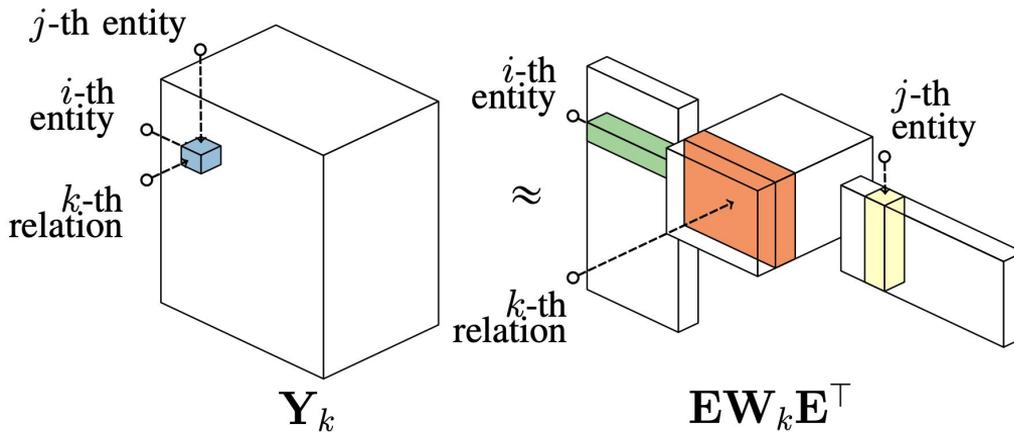
Goal - factorize a sparse 3D tensor to dense E and R



KGE - RESCAL

Tensor Factorization

Goal - factorize a sparse 3D tensor to dense E and R



$$\mathbf{E} : \mathbb{R}^{|E| \times n}$$

$$\mathbf{W} : \mathbb{R}^{|k| \times n \times n}$$

KGE - TransE

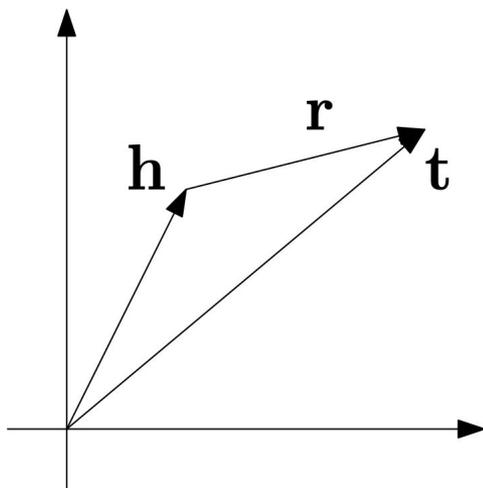
Tensor
Factorization

Translate entities and relations into one embedding space

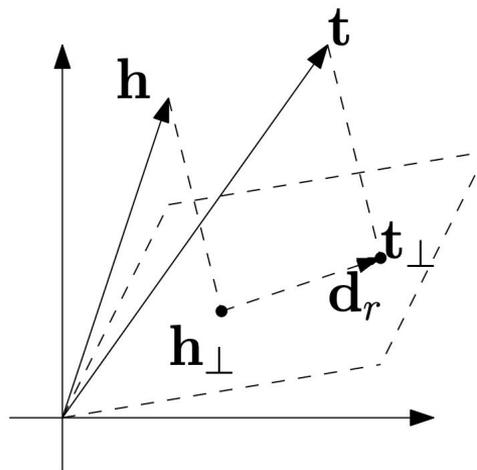
Translation

$$h + r \approx t \quad \text{Moscow} + \text{capitalOf} \approx \text{Russia}$$

$$\|h\|_2^2 = \|t\|_2^2 = 1$$



(a) TransE



(b) TransH

KGE - TransE

Tensor
Factorization

Translation

LOTS of
models

TABLE 9

Knowledge graph embedding using margin-based ranking loss.

GE Algorithm	Energy Function $f_r(h, t)$
TransE [91]	$\ h + r - t\ _{l1}$
TKRL [53]	$\ M_{rh}h + r - M_{rt}t\ $
TransR [15]	$\ hM_r + r - tM_r\ _2^2$
CTransR [15]	$\ hM_r + r_c - tM_r\ _2^2 + \alpha\ r_c - r\ _2^2$
TransH [14]	$\ (h - w_r^T h w_r) + d_r - (t - w_r^T t w_r)\ _2^2$
SePLi [39]	$\frac{1}{2}\ W_i e_{ih} + b_i - e_{it}\ _2^2$
TransD [125]	$\ M_{rh}h + r - M_{rt}t\ _2^2$
TranSparse [126]	$\ M_r^h(\theta_r^h)h + r - M_r^t(\theta_r^t)t\ _{l1/2}^2$
m-TransH [127]	$\ \sum_{\rho \in \mathcal{M}(R_r)} a_r(\rho) \mathbb{P}_{n_r}(t(\rho)) + b_r\ ^2, t \in \mathcal{N}^{\mathcal{M}(R_r)}$
DKRL [128]	$\ h_d + r - t_d\ + \ h_d + r - t_s\ + \ h_s + r - t_d\ $
ManifoldE [129]	Sphere: $\ \varphi(h) + \varphi(r) - \varphi(t)\ ^2$ Hyperplane: $(\varphi(h) + \varphi(r_{head}))^T(\varphi(t) + \varphi(r_{tail}))$ φ is the mapping function to Hilbert space
TransA [130]	$\ h + r - t\ $
puTransE [43]	$\ h + r - t\ $
KGE-LDA [60]	$\ h + r - t\ _{l1}$
SE [90]	$\ R_u h - R_u t\ _{l1}$
SME [92] linear	$(W_{u1}r + W_{u2}h + b_u)^T(W_{v1}r + W_{v2}t + b_v)$
SME [92] bilinear	$(W_{u1}r + W_{u2}h + b_u)^T(W_{v1}r + W_{v2}t + b_v)$
SSP [59]	$-\lambda\ e - s^T e s\ _2^2 + \ e\ _2^2, S(s_h, s_t) = \frac{s_h + s_t}{\ s_h + s_t\ _2}$
NTN [131]	$u_r^T \tanh(h^T W_r t + W_{rh}h + W_{rt}t + b_r)$
HOLE [132]	$r^T(h \star t)$, where \star is circular correlation
MTransE [133]	$\ h + r - t\ _{l1}$

KGE - Incorporating OWL Rules

Tensor
Factorization

$$\min_{\theta} \sum_{(h,r,t) \in \mathcal{S}} \alpha_{h,t}^r \log(1 + \exp(-y_{h,t}^r f_{h,t}^r)) + \lambda \sum_{i=1}^l \frac{\mathcal{R}_i}{N_i}$$

subject to $\|h\| = 1$ and $\|t\| = 1$.

Translation

Rule	Definition $\forall \mathbf{h}, \mathbf{t}, \mathbf{s} \in \mathcal{E} : \dots$	Formulation based on score function	Formulation based on NN	Equivalent regularization form (Denoted as \mathcal{R}_i in Equation (2))
Equivalence	$(\mathbf{h}, r_1, \mathbf{t}) \Leftrightarrow (\mathbf{h}, r_2, \mathbf{t})$	$f_{h,t}^{r_1} = f_{h,t}^{r_2} + \xi_{h,t}$	$\Phi_{h,t}^T (\beta^{r_1} - \beta^{r_2}) = \xi_{h,t}$	$\max(\ \beta^{r_1} - \beta^{r_2}\ _1 - \xi_{\text{Eq}}, 0)$
Symmetric	$(\mathbf{h}, r, \mathbf{t}) \Leftrightarrow (\mathbf{t}, r, \mathbf{h})$	$f_{h,t}^r = f_{t,h}^r + \xi_{h,t}$	$(\Phi_{h,t} - \Phi_{t,h})^T \beta^r = \xi_{h,t}$	$\max((\Phi_{h,t} - \Phi_{t,h})^T \beta^r - \xi_{\text{Sy}}, 0)$
Asymmetric	$(\mathbf{h}, r, \mathbf{t}) \Rightarrow \neg(\mathbf{t}, r, \mathbf{h})$	$f_{h,t}^r = f_{t,h}^r + \mathcal{M}_{h,t}$	$(\Phi_{h,t} - \Phi_{t,h})^T \beta^r = \mathcal{M}$	NC
Negation	$(\mathbf{h}, r_1, \mathbf{t}) \Leftrightarrow \neg(\mathbf{h}, r_2, \mathbf{t})$	$f_{h,t}^{r_1} = \mathcal{M} - f_{h,t}^{r_2} + \xi_{h,t}$	$\Phi_{h,t}^T (\beta^{r_1} + \beta^{r_2}) = \mathcal{M} + \xi_{h,t}$	NC
Implication	$(\mathbf{h}, r_1, \mathbf{t}) \Rightarrow (\mathbf{h}, r_2, \mathbf{t})$	$f_{h,t}^{r_1} \leq f_{h,t}^{r_2}$	$\Phi_{h,t}^T (\beta^{r_1} - \beta^{r_2}) \leq 0$	$\max(\sum_i (\beta_i^{r_1} - \beta_i^{r_2}) + \xi_{\text{Im}}, 0)$
Inverse	$(\mathbf{h}, r_1, \mathbf{t}) \Rightarrow (\mathbf{t}, r_2, \mathbf{h})$	$f_{h,t}^{r_1} \leq f_{t,h}^{r_2}$	$\Phi_{h,t}^T \beta^{r_1} - \Phi_{t,h}^T \beta^{r_2} \leq 0$	$\max(\Phi_{h,t}^T \beta^{r_1} - \Phi_{t,h}^T \beta^{r_2} + \xi_{\text{In}}, 0)$
Reflexivity	$(\mathbf{h}, r, \mathbf{h})$	$f_{h,h}^r = \mathcal{M} - \xi_{h,h}$	$\Phi_{h,h}^T \beta^r = \mathcal{M} - \xi_{h,h}$	NC
Irreflexive	$\neg(\mathbf{h}, r, \mathbf{h})$	$f_{h,h}^r = \xi_{h,h}$	$\Phi_{h,h}^T \beta^r = \xi_{h,h}$	NC
Transitivity	$(\mathbf{h}, r, \mathbf{t}) \wedge (\mathbf{t}, r, \mathbf{s}) \Rightarrow (\mathbf{h}, r, \mathbf{s})$	$\sigma(f_{h,s}^r) \geq \sigma(f_{h,t}^r) \times \sigma(f_{t,s}^r)$	$\sigma(\Phi_{h,t} \beta^r) \times \sigma(\Phi_{t,s} \beta^r) - \sigma(\Phi_{h,s} \beta^r) \leq 0$	$\max(\sigma(\Phi_{h,t} \beta^r) \times \sigma(\Phi_{t,s} \beta^r) - \sigma(\Phi_{h,s} \beta^r) + \xi_{\text{Tr}}, 0)$
Composition	$(\mathbf{h}, r_1, \mathbf{t}) \wedge (\mathbf{t}, r_2, \mathbf{s}) \Rightarrow (\mathbf{h}, r_3, \mathbf{s})$	$\sigma(f_{h,s}^{r_1}) \geq \sigma(f_{h,t}^{r_2}) \times \sigma(f_{t,s}^{r_3})$	$\sigma(\Phi_{h,t} \beta^{r_1}) \times \sigma(\Phi_{t,s} \beta^{r_2}) - \sigma(\Phi_{h,s} \beta^{r_3}) \leq 0$	$\max(\sigma(\Phi_{h,t} \beta^{r_1}) \times \sigma(\Phi_{t,s} \beta^{r_2}) - \sigma(\Phi_{h,s} \beta^{r_3}) + \xi_{\text{Co}}, 0)$

Table 1: Formulation and representation of rules (NC: Not considered for implementation).

KGE - RotatE

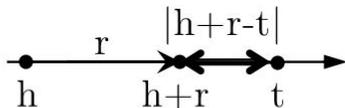
Tensor
Factorization

Translation

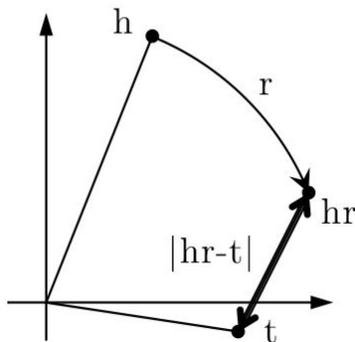
Idea:

Entities are vectors
in **complex space**

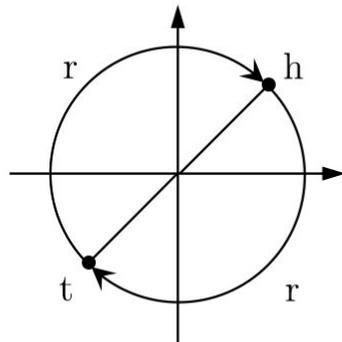
Relations: rotations
in **complex space**



(a) TransE models r as translation in real line.



(b) RotatE models r as rotation in complex plane.



(c) RotatE: an example of modeling symmetric relations r with $r_i = -1$

Figure 1: Illustrations of TransE and RotatE with only 1 dimension of embedding.

Score function:

$$d_r(\mathbf{h}, \mathbf{t}) = \|\mathbf{h} \circ \mathbf{r} - \mathbf{t}\| \quad |\mathbf{r}_i| = 1$$

Loss & Optimization:

$$L = -\log \sigma(\gamma - d_r(\mathbf{h}, \mathbf{t})) - \sum_{i=1}^n \frac{1}{k} \log \sigma(d_r(\mathbf{h}'_i, \mathbf{t}'_i) - \gamma),$$

KGE - RotatE & Patterns

Translation

Model	Score Function	Symmetry	Antisymmetry	Inversion	Composition
SE	$-\ \mathbf{W}_{r,1}\mathbf{h} - \mathbf{W}_{r,2}\mathbf{t}\ $	✗	✗	✗	✗
TransE	$-\ \mathbf{h} + \mathbf{r} - \mathbf{t}\ $	✗	✓	✓	✓
TransX	$-\ g_{r,1}(\mathbf{h}) + \mathbf{r} - g_{r,2}(\mathbf{t})\ $	✓	✓	✗	✗
DistMult	$\langle \mathbf{h}, \mathbf{r}, \mathbf{t} \rangle$	✓	✗	✗	✗
Complex	$\text{Re}(\langle \mathbf{h}, \mathbf{r}, \bar{\mathbf{t}} \rangle)$	✓	✓	✓	✗
RotatE	$-\ \mathbf{h} \circ \mathbf{r} - \mathbf{t}\ $	✓	✓	✓	✓

Table 2: The pattern modeling and inference abilities of several models.

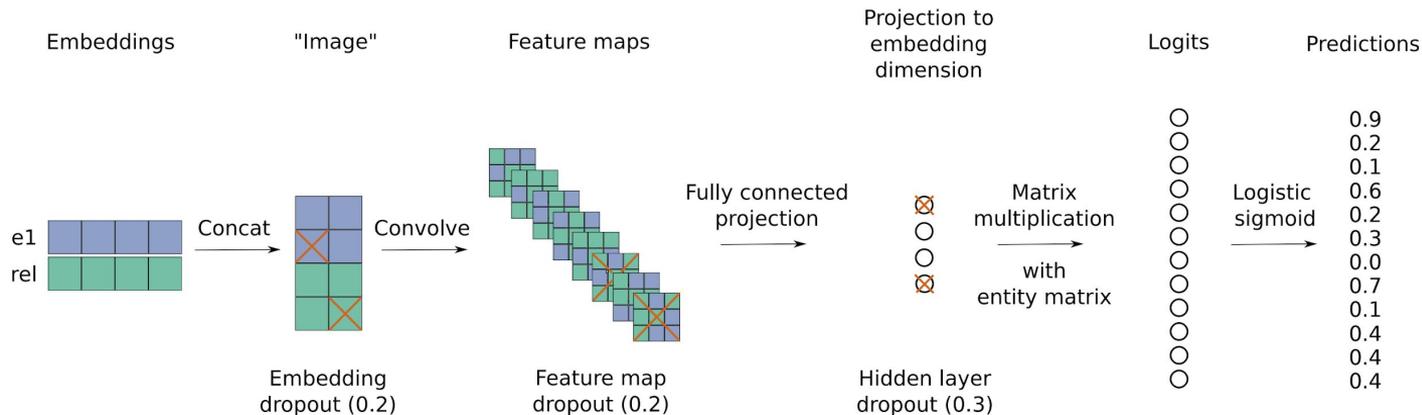
KGE - ConvE

Tensor
Factorization

Translation

Convolution

Goal: CNNs for predicting a probability of the object



Score function:
$$\psi_r(\mathbf{e}_s, \mathbf{e}_o) = f(\text{vec}(f([\overline{\mathbf{e}}_s; \overline{\mathbf{r}}_r] * \omega))) \mathbf{W} \mathbf{e}_o,$$

Loss & Optimization:
$$\mathcal{L}(p, t) = -\frac{1}{N} \sum_i (t_i \cdot \log(p_i) + (1 - t_i) \cdot \log(1 - p_i)),$$

KGE - CoKE

Tensor
Factorization

Translation

Transformer

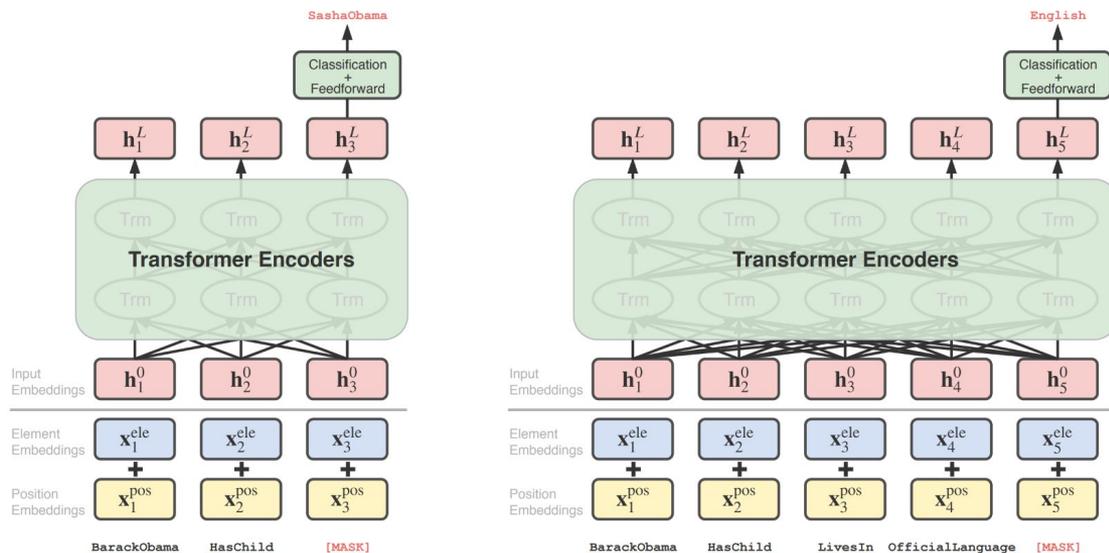


Figure 2: Overall framework of CoKE. An edge (left) or a path (right) is given as an input sequence, with an entity replaced by a special token [MASK]. The input is then fed into a stack of Transformer encoder blocks. The final hidden state corresponding to [MASK] is used to predict the target entity.

KGE - CompGCN Encoder

Tensor
Factorization

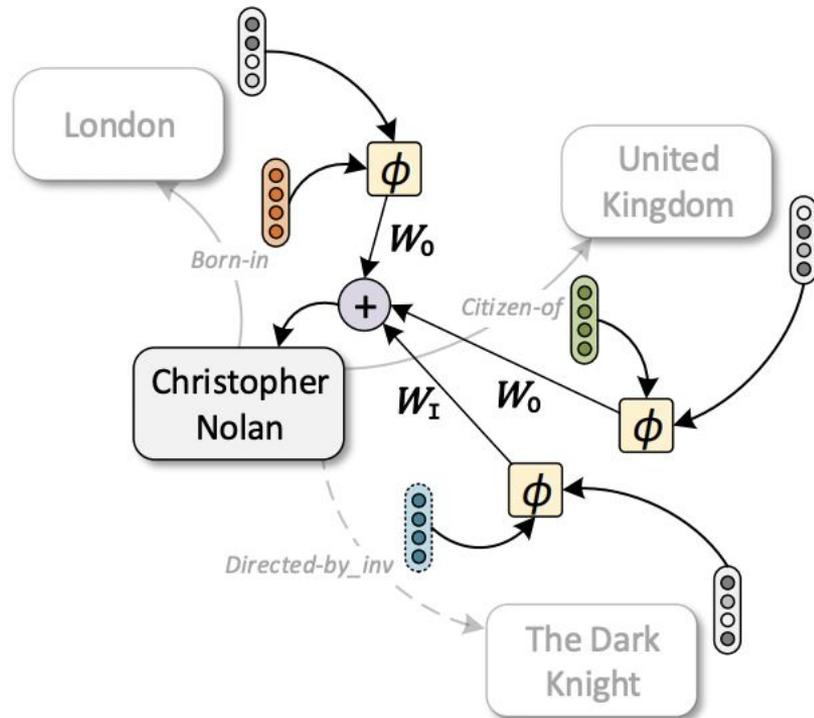
Translation

Transformer

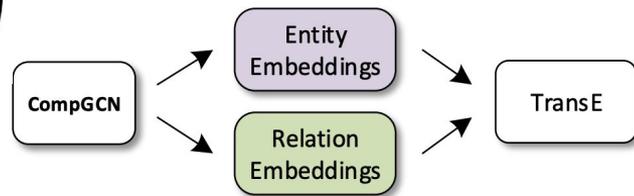
Graph Neural
Nets

- Message Passing
- Encoder-Decoder
- Many architectures

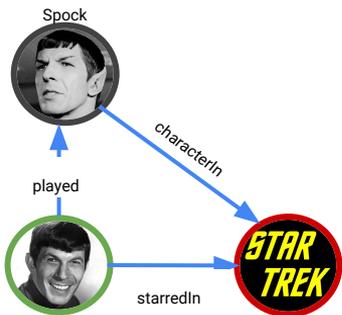
$$h_v = f \left(\sum_{(u,r) \in \mathcal{N}(v)} W_{\lambda(r)} \phi(\mathbf{x}_u, \mathbf{z}_r) \right)$$



CompGCN Update



KGE - Training



Optimization

Loss Function

Negative Sampling

Entity matrix

$$E : \mathbb{R}^{|E| \times n}$$

$$\text{Spock} = [0.1, 0.2, 0.3]$$

$$\text{Leonard Nimoy} = [0.4, 0.8, 0.1]$$

$$\text{Star Trek} = [0.22, 0.34, 0.87]$$

Relations matrix

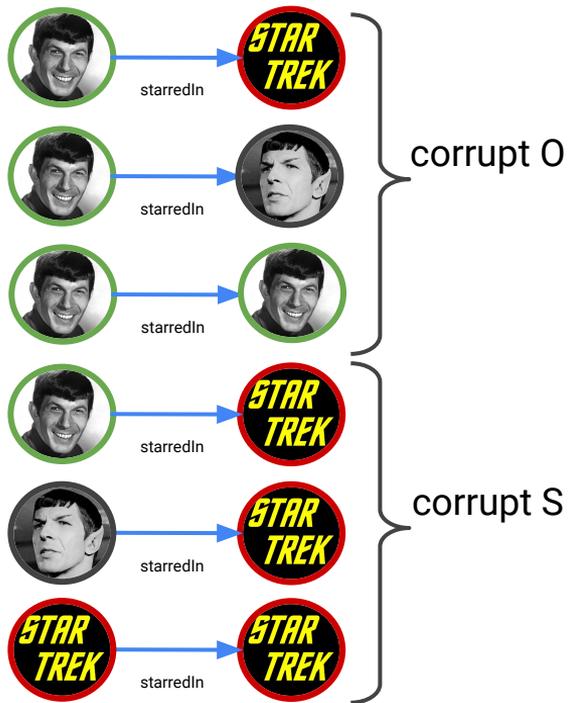
$$W : \mathbb{R}^{|k| \times n}$$

$$\text{characterIn} = [0.1, 0.1, 0.6]$$

$$\text{played} = [0.2, 0.3, 0.4]$$

$$\text{starredIn} = [0.9, -0.2, 0.1]$$

KGE - Training - Negative Sampling + Margin Loss



$$L(\Omega) = \sum_{(e_1, r, e_2) \in T} \sum_{(e'_1, r, e'_2) \in T'} \max\{S_{(e'_1, r, e'_2)} - S_{(e_1, r, e_2)} + 1, 0\}$$

Negative sampling: incorrect triples should have lower (higher) score than correct triples

$$f \left(\text{actor} \xrightarrow{\text{starredIn}} \text{STAR TREK} \right) > f \left(\text{STAR TREK} \xrightarrow{\text{starredIn}} \text{STAR TREK} \right)$$

Big Picture in \mathbb{R}^5

Transductive

Triples

Supervised

Unimodal

Small

Inductive

Hyper-relational

Unsupervised

Multimodal

Large (sampling)

SETTING

TASK

Link prediction

Node classification

Entity Matching

Query Embedding

Theoretical
Understanding

Graph Encoder

Knowledge Graph

Conclusion

