

# Applied Machine Learning

Maximum Likelihood and Bayesian Reasoning

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COMP 551 (winter 2022)<sub>2</sub>

# Admin

- Self-enrolment in groups is due **tonight** afterwards anyone left will be assigned a group, make sure to fill the poll if not already for automatic assignments
- Correction, If you need to be moved between groups, please send an email and cc your group members, i.e. whoever will be affected by the change/correction
- Please do not ask for exceptions to group size
- Questions?

# Objectives

understand what it means to learn a probabilistic model of the data

- using maximum likelihood principle
- using Bayesian inference
  - prior, posterior, posterior predictive
  - MAP inference
  - Beta-Bernoulli conjugate pairs

# Parameter estimation

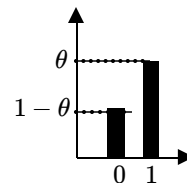
a coin's head/tail outcome has a **Bernoulli distribution**



$$\text{Bernoulli}(x|\theta) = \theta^x (1 - \theta)^{(1-x)}$$

reminder: Bernoulli random variable takes values of 0 or 1, e.g. head/tail in a coin toss

$$p(x|\theta) = \begin{cases} \theta & x = 1 \\ 1 - \theta & x = 0 \end{cases}$$



this is our **probabilistic model** of some head/tail IID data  $\mathcal{D} = \{0, 0, 1, 1, 0, 0, 1, 0, 0, 1\}$

**Objective:** learn the model parameter  $\theta$

since we are only interested in the counts, we can also use **Binomial distribution**

$$\text{Binomial}(N, N_h|\theta) = \binom{N}{N_h} \theta^{N_h} (1 - \theta)^{N - N_h}$$

$|\mathcal{D}|$

# heads  $N_h = \sum_{x \in \mathcal{D}} x$

$N_t$

# Maximum likelihood

a coin's head/tail outcome has a **Bernoulli distribution**



$$\text{Bernoulli}(x|\theta) = \theta^x (1 - \theta)^{(1-x)}$$

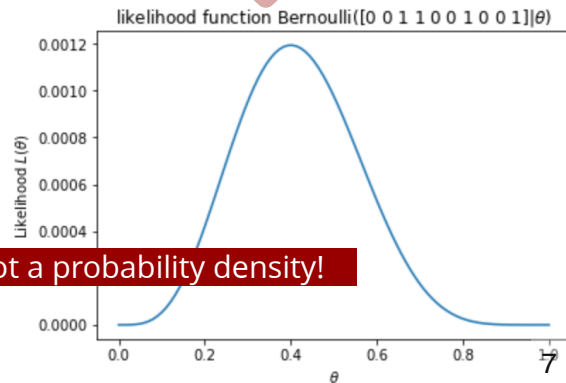
this is our **probabilistic model** of some head/tail IID data  $\mathcal{D} = \{0, 0, 1, 1, 0, 0, 1, 0, 0, 1\}$

**Objective:** learn the model parameter  $\theta$

**Idea:** find the parameter  $\theta$  that maximizes the probability of observing  $\mathcal{D}$

**Likelihood**  $L(\theta; \mathcal{D}) = \prod_{x \in \mathcal{D}} \text{Bernoulli}(x|\theta) = \theta^4 (1 - \theta)^6$  is a function of  $\theta$

**Max-likelihood** assignment



note that this is not a probability density!

# Maximizing log-likelihood

**likelihood**  $L(\theta; \mathcal{D}) = \prod_{x \in \mathcal{D}} p(x; \theta)$

*using product here creates extreme values*

*for 100 samples in our example, the likelihood shrinks below 1e-30*

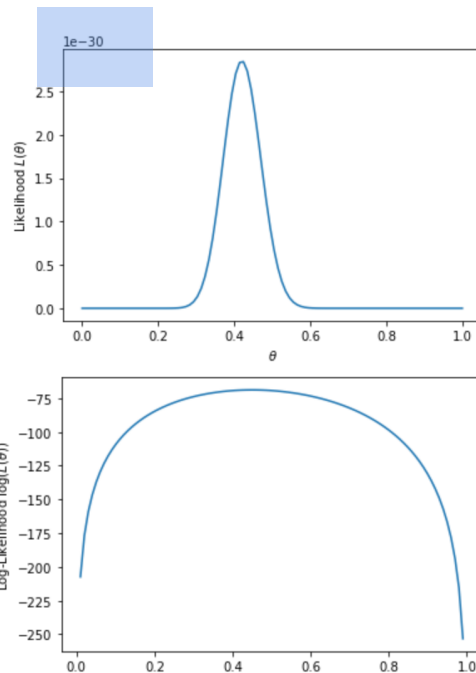
**log-likelihood** has the same maximum but it is well-behaved

$$\ell(\theta; \mathcal{D}) = \log(L(\theta; \mathcal{D})) = \sum_{x \in \mathcal{D}} \log(p(x; \theta))$$

how do we find the max-likelihood parameter?  $\theta^* = \arg \max_{\theta} \ell(\theta; \mathcal{D})$

*for some simple models we can get the **closed form solution***

*for complex models we need to use **numerical optimization***



# Maximizing log-likelihood

**log-likelihood**  $\ell(\theta; \mathcal{D}) = \log(L(\theta; \mathcal{D})) = \sum_{x \in \mathcal{D}} \log(\text{Bernoulli}(x; \theta))$

**observation:** at maximum, the derivative of  $\ell(\theta; \mathcal{D})$  is zero

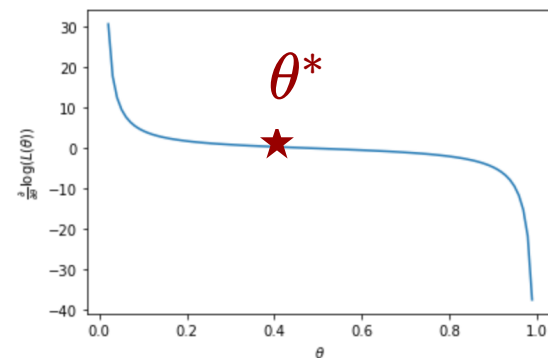
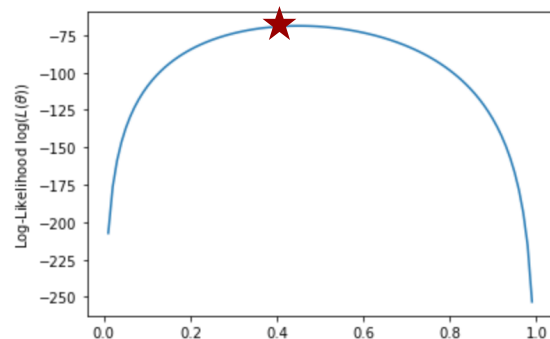
**idea:** set the the derivative to zero and solve for  $\theta$

**example** max-likelihood for Bernoulli

$$\begin{aligned}\frac{\partial}{\partial \theta} \ell(\theta; \mathcal{D}) &= \frac{\partial}{\partial \theta} \sum_{x \in \mathcal{D}} \log(\theta^x (1 - \theta)^{(1-x)}) \\ &= \frac{\partial}{\partial \theta} \sum_x x \log \theta + (1 - x) \log(1 - \theta) \\ &= \sum_x \frac{x}{\theta} - \frac{1-x}{1-\theta} = 0\end{aligned}$$

which gives  $\theta^{MLE} = \frac{\sum_{x \in \mathcal{D}} x}{|\mathcal{D}|}$  is simply the portion of heads in our dataset

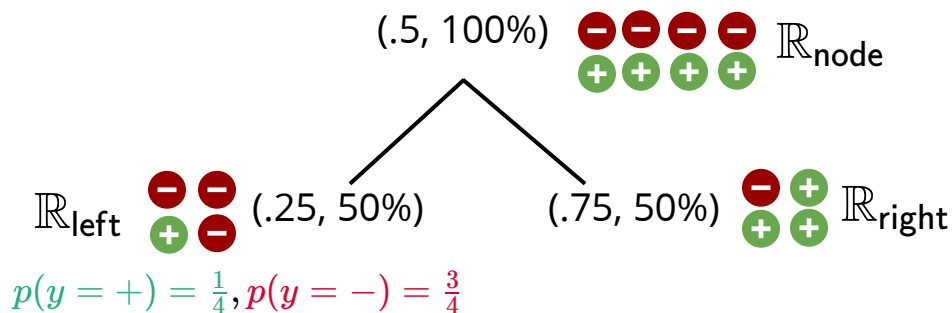
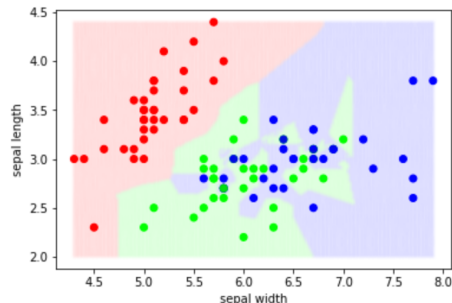
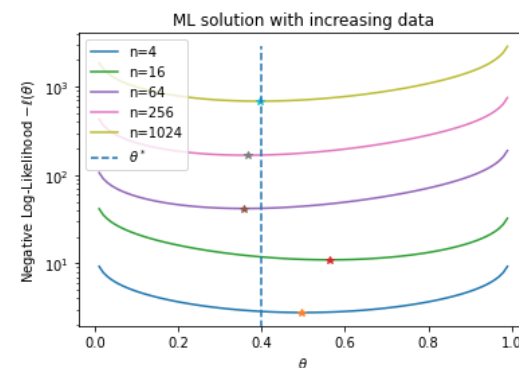
what is  $\theta^{MLE}$  when  $\mathcal{D} = \{0, 0, 1, 1, 0, 0, 1, 0, 0, 1\}$ ?



# Bayesian approach

max-likelihood estimate does not reflect our uncertainty:

- e.g.,  $\theta^{MLE} = .2$  for both 1/5 heads and 1000/5000 heads
  - in which case are we more certain of the predicted  $\theta$ ?



How can we quantify our uncertainty about our prediction?



# Bayesian approach

How can we quantify our uncertainty about our prediction?

capture it using a conditional probability distribution instead of a single best guess

Using the Bayesian inference approach

- we maintain a *distribution* over parameters  $p(\theta)$  prior what do we believe about  $\theta$  before any observation
- after observing  $\mathcal{D}$  we update this distribution  $p(\theta|\mathcal{D})$  posterior

how to update degree of certainty given data? using **Bayes rule**

$$\underset{\text{observed}}{\overset{\text{hidden}}{p(\theta|\mathcal{D})}} = \frac{\underset{\text{prior}}{p(\theta)} \overset{\text{likelihood of the data}}{p(\mathcal{D}|\theta)} \text{ previously denoted by } L(\theta; \mathcal{D})}{p(\mathcal{D})}$$

**evidence:** this is a normalization, **marginal likelihood of data**

We can get a point estimate by collapsing this posterior distribution to a single point, i.e. the best guess

$$p(\mathcal{D}) = \int p(\theta') p(\mathcal{D}|\theta') d\theta'$$

# Bayes rule: example reminder

$c = \{\text{yes}, \text{no}\}$  patient having cancer?

$x \in \{-, +\}$  observed test results, a single binary feature

prior: .1% of population has cancer  $p(\text{yes}) = .001$

likelihood:  $p(+|\text{yes}) = .9$  TP rate of the test (90%)

$$p(c = \text{yes} \mid x) = \frac{p(c=\text{yes})p(x|c=\text{yes})}{p(x)}$$

posterior:  $p(\text{yes}|+) = .0177$

FP rate of the test (5%)

evidence:  $p(+) = p(\text{yes})p(+|\text{yes}) + p(\text{no})p(+|\text{no}) = .001 \times .9 + .999 \times .05 = .05$

# Conjugate Priors



in our coin example, we know the form of likelihood:

prior	$p(\theta)?$
posterior	$p(\theta \mathcal{D})?$
likelihood	$p(\mathcal{D} \theta) = \prod_{x \in \mathcal{D}} \text{Bernoulli}(x; \theta) = \theta^{N_h} (1 - \theta)^{N_t}$

$$\text{posterior} \overset{\text{proportional}}{\propto} \text{prior} \times \text{likelihood}$$
$$p(\theta : \alpha') \propto p(\theta : \alpha) \times p(\mathcal{D}|\theta)$$

conjugate

To simplify the computation we want prior and posterior to have the **same form**

this gives us the following form  $p(\theta|a, b) \propto \theta^a (1 - \theta)^b$

this means there is a normalization constant that does not depend on  $\theta$

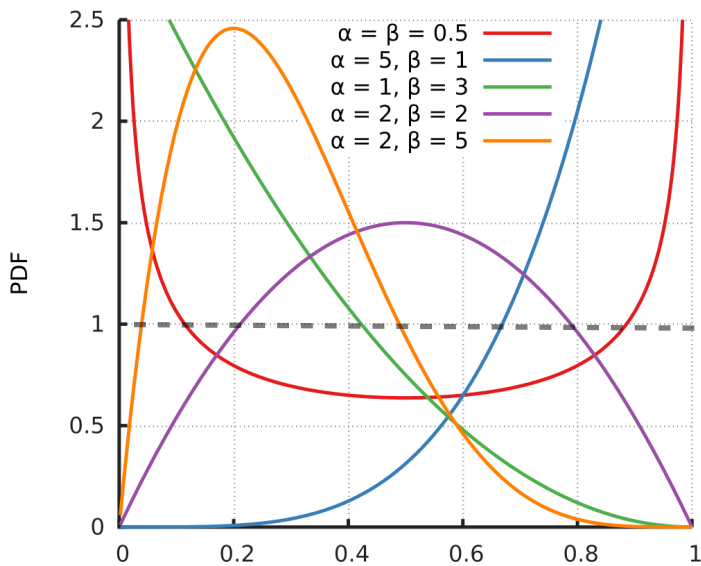
↓  
distribution of this form has a name, **Beta** distribution

we say Beta distribution is a conjugate prior to the Bernoulli likelihood

(so that we can easily update our belief with new observations)

# Beta distribution

**Beta distribution** has the following density



$$\text{Beta}(\theta|\alpha, \beta) = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha-1} (1-\theta)^{\beta-1}$$

$\alpha, \beta > 0$

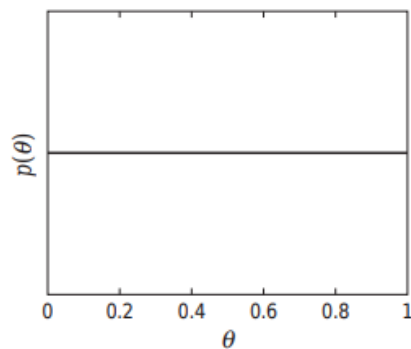
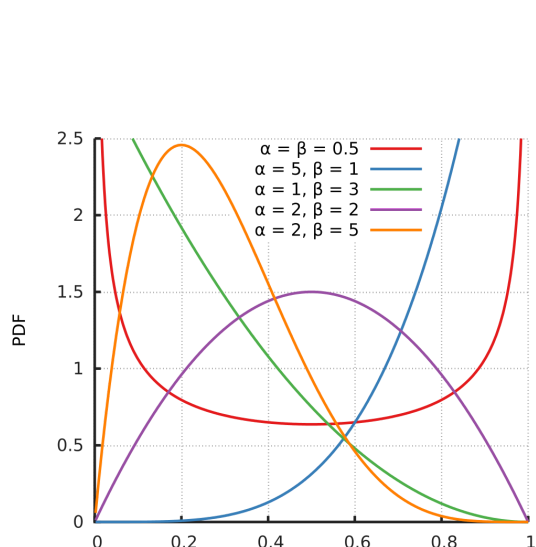
normalization  
 $\Gamma$  is the generalization of factorial to real number  $\Gamma(a+1) = a\Gamma(a)$

$\text{Beta}(\theta|\alpha = \beta = 1)$  is uniform

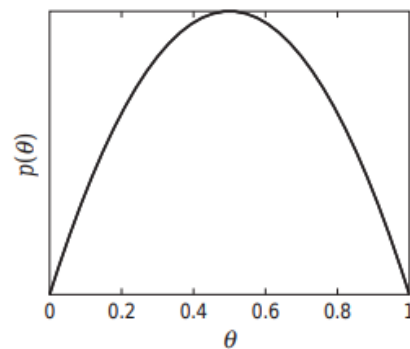
mean of the distribution is  $\mathbb{E}[\theta] = \frac{\alpha}{\alpha+\beta}$

for  $\alpha, \beta > 1$  the dist. is unimodal; its mode is  $\frac{\alpha-1}{\alpha+\beta-2}$

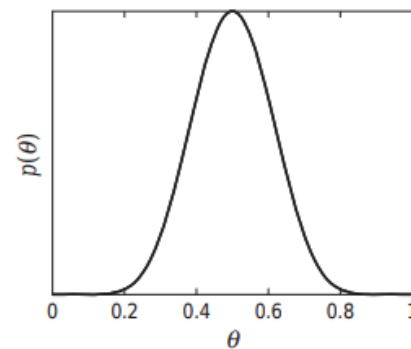
# Beta distribution: more examples



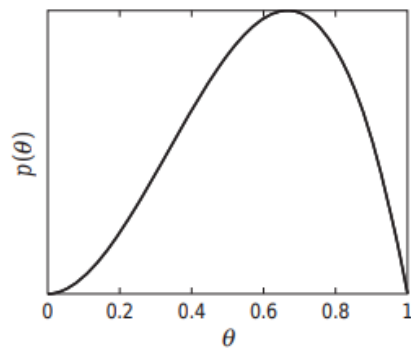
*Beta(1,1)*



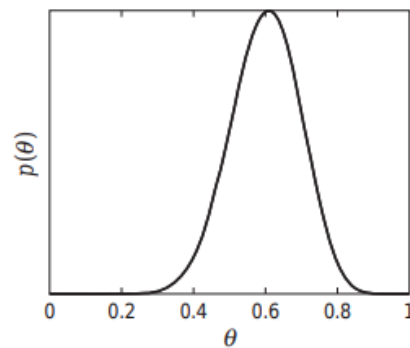
*Beta(2,2)*



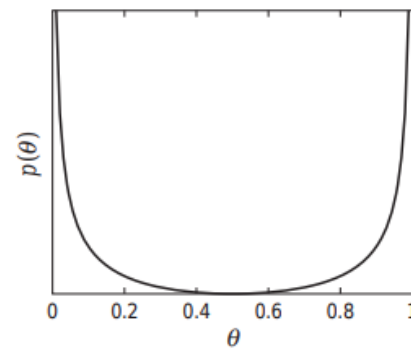
*Beta(10,10)*



*Beta(3,2)*



*Beta(15,10)*



*Beta(0.5,0.5)*

# Beta-Bernoulli conjugate pair

how to model probability of heads when we toss a coin  $N$  times



$$\text{posterior} \overset{\text{proportional}}{\propto} \text{prior} \times \text{likelihood}$$

$$\text{prior} \quad p(\theta) \propto \theta^{\alpha-1} (1 - \theta)^{\beta-1}$$

$$p(\theta) = \text{Beta}(\theta|\alpha, \beta)$$

$$\text{likelihood} \quad p(\mathcal{D}|\theta) = \theta^{N_h} (1 - \theta)^{N_t}$$

$$L(\theta; \mathcal{D}) = \prod \text{Bernoulli}(N_h, N_t|\theta)$$

*product of Bernoulli likelihoods  
equivalent to Binomial likelihood*

$$\text{posterior} \quad p(\theta|\mathcal{D}) \propto \theta^{\alpha+N_h-1} (1 - \theta)^{\beta+N_t-1}$$

$$p(\theta|\mathcal{D}) = \text{Beta}(\theta|\alpha + N_h, \beta + N_t)$$

$\alpha, \beta$  are called *pseudo-counts*

their effect is similar to imaginary observation of heads (  $\alpha$  ) and tails (  $\beta$  )

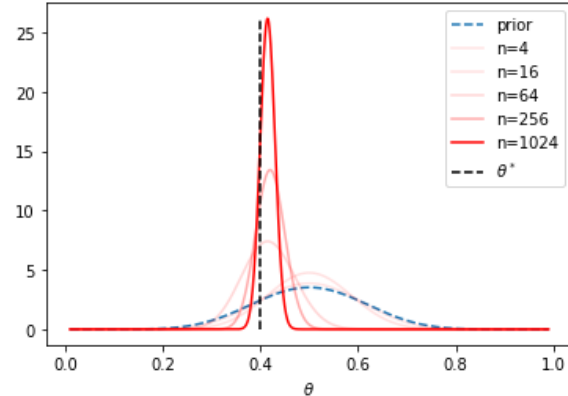
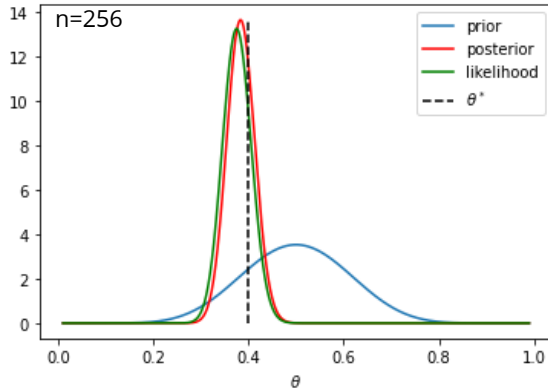
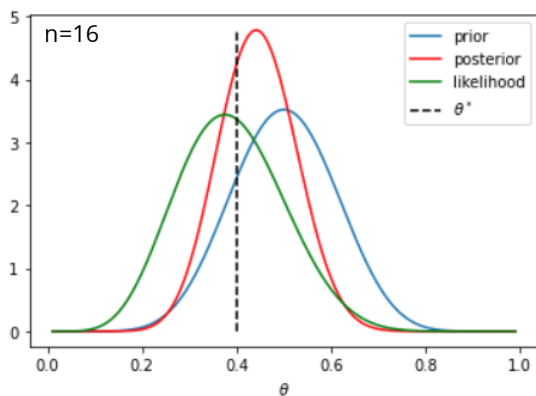
# Effect of more data

with few observations, prior has a high influence  
as we increase the number of observations  $N = |\mathcal{D}|$  the effect of prior diminishes  
the likelihood term dominates the posterior

**example** prior  $\text{Beta}(\theta|10,10)$

plot of the **posterior** density with **n** observations

$$p(\theta|\mathcal{D}) \propto \theta^{10+H} (1 - \theta)^{10+N-H}$$



# Posterior predictive

our goal was to estimate the parameters (  $\theta$  ) so that we can make predictions

what if we use the maximum likelihood estimate for the best parameter,  $\theta^{MLE}$ , and plug it in the  $p(x|\theta)$  to make the prediction?

## Example:

if we see four heads in a row, what is the probability of seeing a tail next?

if  $\mathcal{D} = \{1, 1, 1, 1\}$ , what is  $\theta^{MLE}$ ? 1.0

$$\Rightarrow 1 - \theta^{MLE} = 0.0$$

$$p(0|\theta) = \theta^0(1 - \theta)^{(1-0)} = 1 - \theta$$

Next, let's use the posterior distribution we learn through Bayesian inference



# Posterior predictive

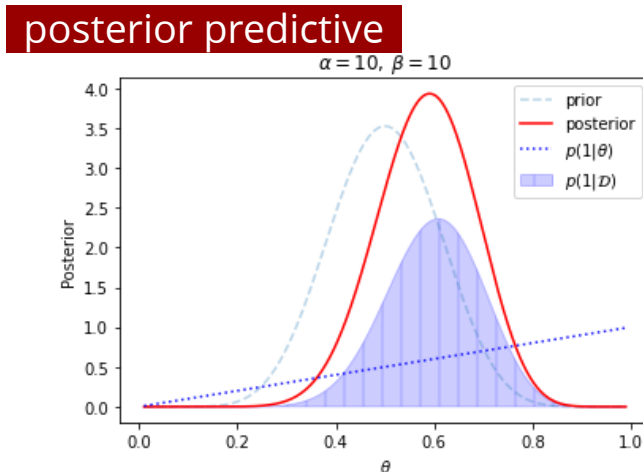
our goal was to estimate the parameters (  $\theta$  ) so that we can make predictions

now we have a **(posterior) distribution** over parameters,  $p(\theta|\mathcal{D})$ , rather than a single  $\theta^{MLE}$   
 $\theta^{MLE}$  only gives a single best guess based on that parameter,  $p(x|\theta)$

To make predictions, we calculate the average prediction over all possible values of  $\theta$

$$p(x|\mathcal{D}) = \int_{\theta} p(\theta|\mathcal{D})p(x|\theta)d\theta$$

for each possible  $\theta$ , weight the prediction by the posterior probability of that parameter being true



# Posterior predictive

our goal was to estimate the parameters ( $\theta$ ) so that we can make predictions

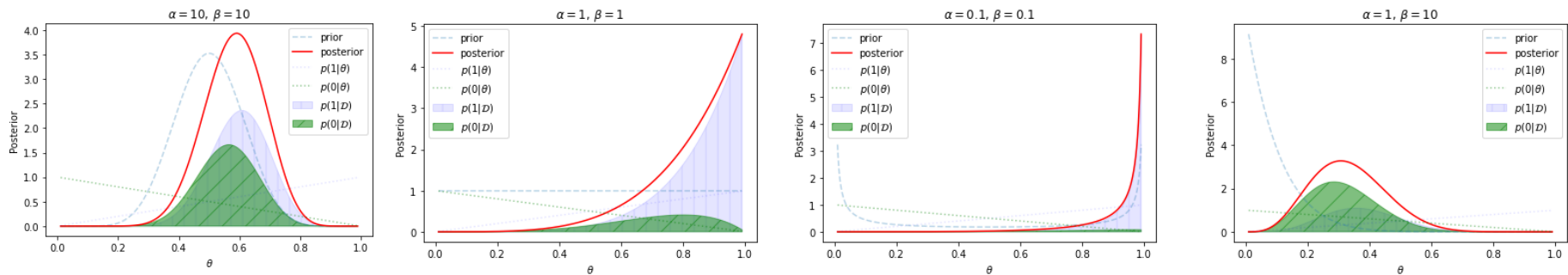
now we have a (posterior) **distribution** over parameters,  $p(\theta|\mathcal{D})$

To make predictions, we calculate the average prediction over all possible values of  $\theta$

## Example

if we see four heads in a row, what is the probability of seeing a tail next?

if  $\mathcal{D} = \{1, 1, 1, 1\}$ , what is  $p(0|\mathcal{D})$ ? depends on our prior belief



when the strength of prior gets close to zero the prediction becomes similar to MLE

# Posterior predictive for Beta-Bernoulli

start from a Beta prior  $p(\theta) = \text{Beta}(\theta|\alpha, \beta)$

observe  $N_h$  heads and  $N_t$  tails, the posterior is  $p(\theta|\mathcal{D}) = \text{Beta}(\theta|\alpha + N_h, \beta + N_t)$

Given this estimate of the parameters from training data,  
how can we predict the future?

what is the probability that the next coin flip is head?

$$\begin{aligned} p(x = 1|\mathcal{D}) &= \int_{\theta} \text{Bernoulli}(x = 1|\theta) \text{Beta}(\theta|\alpha + N_h, \beta + N_t) d\theta \\ &= \int_{\theta} \theta \text{Beta}(\theta|\alpha + N_h, \beta + N_t) d\theta = \frac{\alpha + N_h}{\alpha + \beta + N} \\ &\quad \text{mean of Beta dist.} \end{aligned}$$

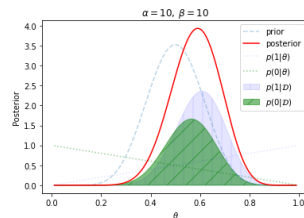
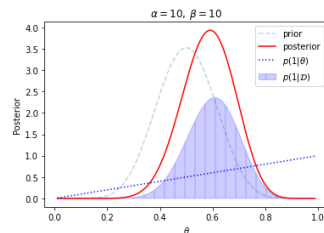
## Example

if we see four heads in a row, what is the probability of seeing a tail next?

if  $\mathcal{D} = \{1, 1, 1, 1\}$ , what is  $p(1|\mathcal{D})$ ?  $\frac{14}{24}$ ,  $p(0|\mathcal{D})$ ?  $\frac{10}{24}$

when we assume the prior is  $\text{Beta}(\alpha = 10, \beta = 10)$

compare with prediction of maximum-likelihood:  $p(x = 1|\mathcal{D}) = \frac{N_h}{N} = 1$ ,  $p(x = 0|\mathcal{D}) = 0$



# Posterior predictive for Beta-Bernoulli

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Given this estimate of the parameters from training data, how can we predict the future?

$$p(x = 1|\mathcal{D}) = \int_{\theta} \text{Bernoulli}(x = 1|\theta) \text{Beta}(\theta|\alpha + N_h, \beta + N_t) d\theta = \frac{\alpha + N_h}{\alpha + \beta + N}$$

compare with prediction of maximum-likelihood:  $p(x = 1|\mathcal{D}) = \frac{N_h}{N}$

if we assume a uniform prior, the posterior predictive is  $p(x = 1|\mathcal{D}) = \frac{N_h + 1}{N + 2}$

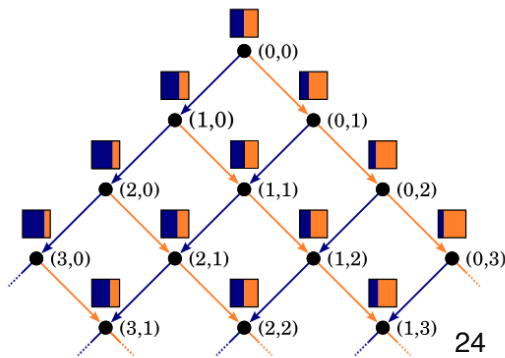
## Laplace smoothing

a.k.a. add-one smoothing  
to avoid ruling out unseen  
cases with zero counts



## Example:

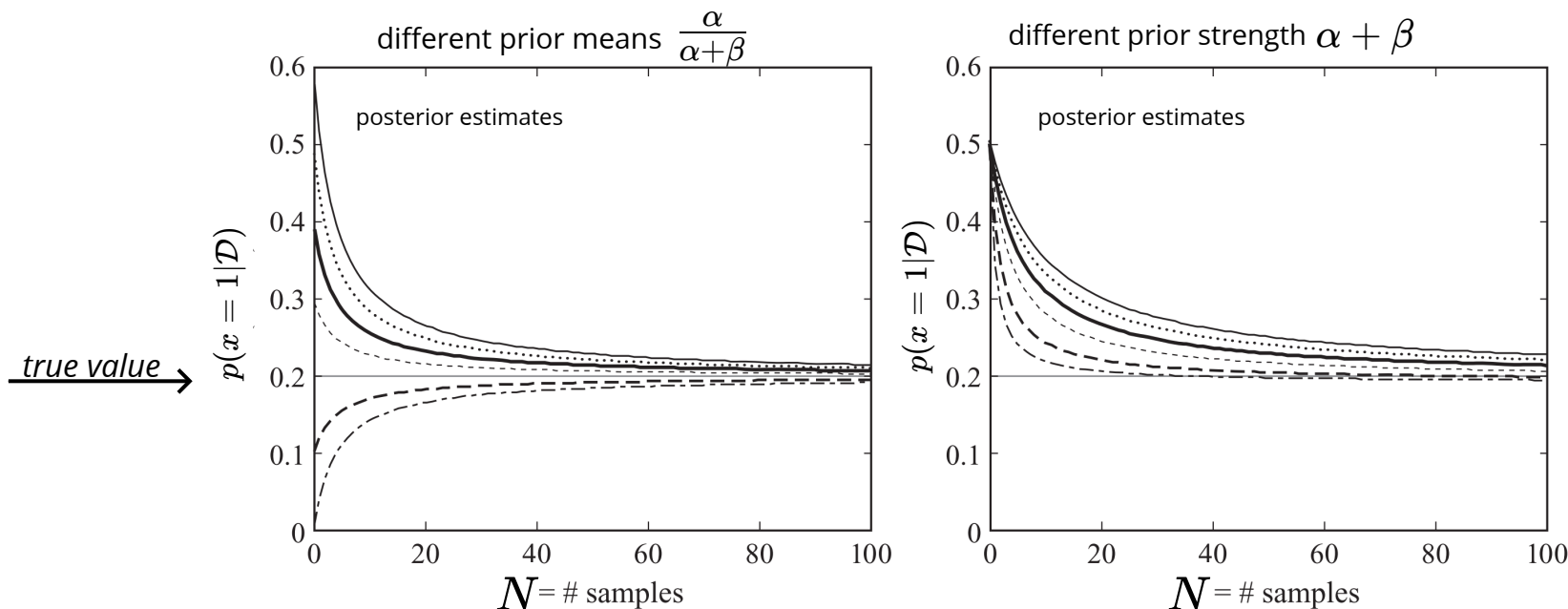
sequential Bayesian  
updating  
with uniform prior  
( $N_h, N_t$ )



# Strength of the prior

with a **strong prior** we need many samples to really change the posterior  
for Beta distribution  $\alpha + \beta$  decides how strong the prior is: how confident we are in our prior

**example** as our dataset grows our estimate becomes more accurate



# Maximum a Posteriori (MAP)

sometimes it is difficult to work with the posterior dist. over parameters

**alternative:** use the parameter with the highest posterior probability  $p(\theta|\mathcal{D})$

MAP estimate

$$\theta^{MAP} = \arg \max_{\theta} p(\theta|\mathcal{D}) = \arg \max_{\theta} p(\theta)p(\mathcal{D}|\theta)$$

compare with max-likelihood estimate *(the only difference is in the prior term)*

$$\theta^{MLE} = \arg \max_{\theta} p(\mathcal{D}|\theta)$$

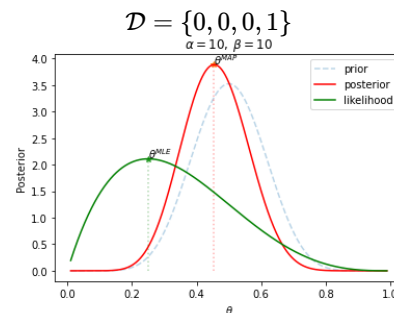
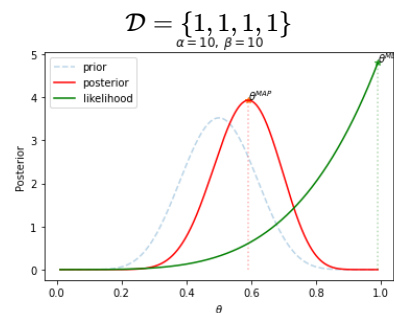
example

for the posterior  $p(\theta|\mathcal{D}) = \text{Beta}(\theta|\alpha + N_h, \beta + N_t)$

MAP estimate is the **mode** of posterior  $\theta^{MAP} = \frac{\alpha + N_h - 1}{\alpha + \beta + N_h + N_t - 2}$

compare with MLE  $\theta^{MLE} = \frac{N_h}{N_h + N_t}$

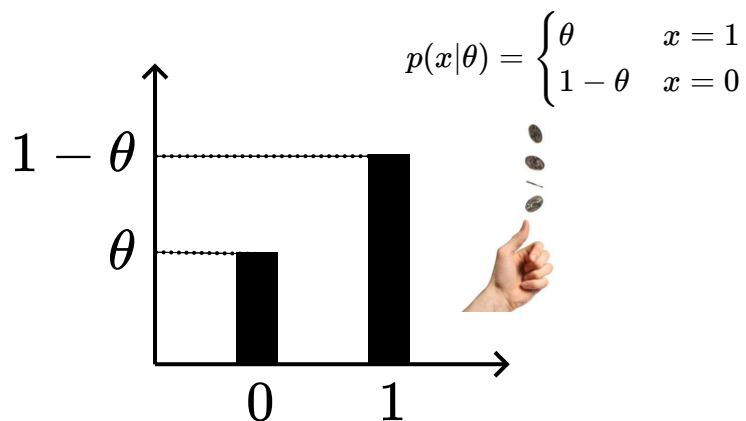
they are equal for uniform prior  $\alpha = \beta = 1$



# Categorical distribution

what if we have more than two categories (e.g., loaded dice instead of coin)  
instead of Bernoulli we have multinoulli or **categorical** dist.

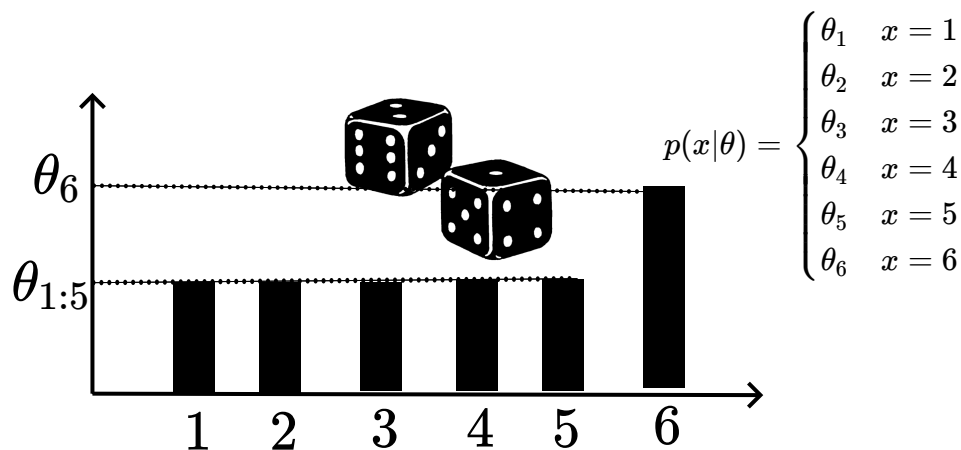
$$\text{Bernoulli}(x|\theta) = \theta^x (1 - \theta)^{(1-x)}$$



once:  
n times:

Bernoulli distribution  
binomial distribution

$$\text{Cat}(x|\theta) = \prod_{k=1}^K \theta_k^{\mathbb{I}(x=k)}$$



categorical distribution  
multinomial distribution


# Categorical distribution

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instead of Bernoulli we have multinoulli or **categorical** dist.

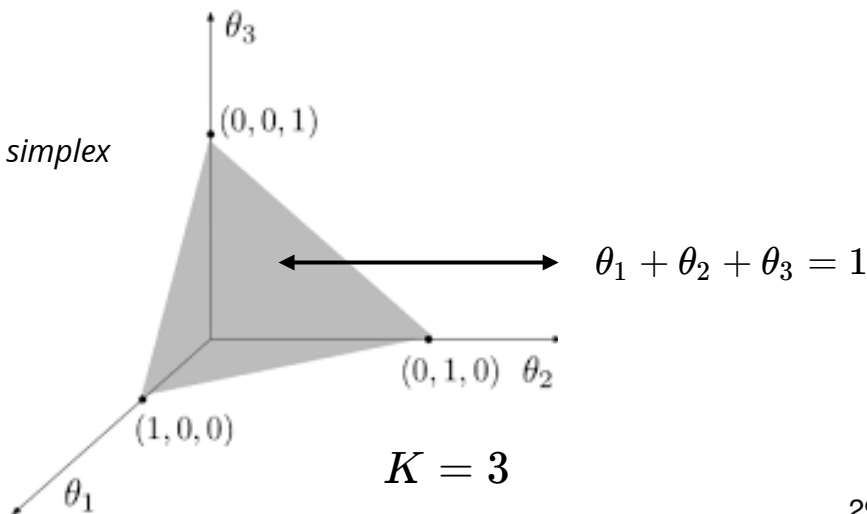
$$\text{Cat}(x|\theta) = \prod_{k=1}^{\text{\# categories}} \theta_k^{\mathbb{I}(x=k)}$$

$$\text{where } \sum_k \theta_k = 1$$

$\theta$  belongs to probability simplex


$$p(x|\theta) = \begin{cases} \theta_1 & x = 1 \\ \theta_2 & x = 2 \\ \theta_3 & x = 3 \\ \theta_4 & x = 4 \\ \theta_5 & x = 5 \\ \theta_6 & x = 6 \end{cases}$$

$$\sum_k^6 \theta_k = 1$$





# Maximum likelihood for categorical dist.

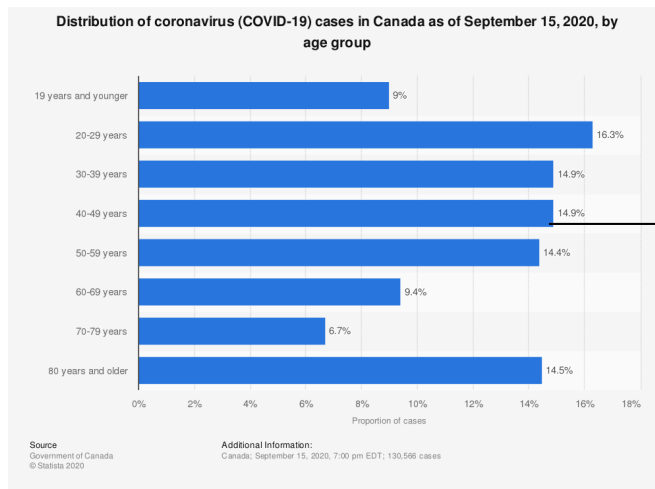
likelihood  $p(\mathcal{D}|\theta) = \prod_{x \in \mathcal{D}} \text{Cat}(x|\theta) = \prod_{x \in \mathcal{D}} \prod_{k=1}^K \theta_k^{\mathbb{I}(x=k)} = \prod_{k=1}^K \theta_k^{N_k}$ ,  $N_k = \sum_{x \in \mathcal{D}} \mathbb{I}(x = k)$

log-likelihood  $\ell(\theta, \mathcal{D}) = \sum_{x \in \mathcal{D}} \sum_k \mathbb{I}(x = k) \log(\theta_k) = \sum_k N_k \log(\theta_k)$

we need to solve  $\frac{\partial}{\partial \theta_k} \ell(\theta, \mathcal{D}) = 0$  subject to  $\sum_k \theta_k = 1$  using Lagrange multipliers

similar to the binary case, max-likelihood estimate is given by data-frequencies  $\theta_k^{MLE} = \frac{N_k}{N}$

example

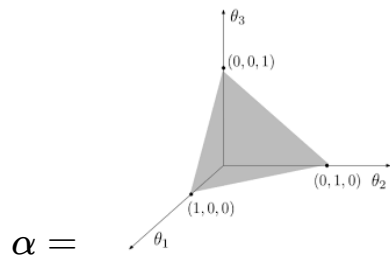


categorical distribution with  $K=8$

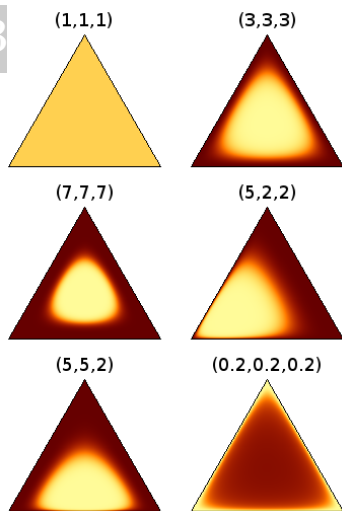
frequencies are max-likelihood parameter estimates

$\rightarrow \theta_5^{MLE} = .149$

# Dirichlet distribution



$K = 3$



$\text{Dir}(\theta, [.2, .2, .2])$

is a distribution over the parameters  $\theta$  of a Categorical dist.

is a generalization of Beta distribution to K categories

this should be a dist. over prob. simplex  $\sum_k \theta_k = 1$

$$\text{Dir}(\theta | \alpha) = \frac{\Gamma(\sum_k \alpha_k)}{\prod_k \Gamma(\alpha_k)} \prod_k \theta_k^{\alpha_k - 1}$$

normalization constant

vector of psedo-counts for K categories (aka concentration parameters)

$\alpha_k > 0 \forall k$

for  $\alpha = [1, \dots, 1]$ , we get uniform distribution

for K=2, it reduces to Beta distribution

# Dirichlet-Categorical conjugate pair

Dirichlet dist.  $\text{Dir}(\theta|\alpha) = \frac{\Gamma(\sum_k \alpha_k)}{\prod_k \Gamma(\alpha_k)} \prod_k \theta_k^{\alpha_k - 1}$  is a conjugate prior for Categorical dist.  $\text{Cat}(x|\theta) = \prod_k \theta_k^{\mathbb{I}(x=k)}$

$$\text{posterior} \propto \text{prior} \times \text{likelihood}$$

$$\text{prior} \quad p(\theta) = \text{Dir}(\theta|\alpha) \propto \prod_k \theta_k^{\alpha_k - 1}$$

$$\text{likelihood} \quad p(\mathcal{D}|\theta) = \prod_k \theta_k^{N_k} \quad \text{we observe } \overset{\eta}{N_1, \dots, N_K} \text{ values from each category}$$

$$\text{posterior} \quad p(\theta|\mathcal{D}) = \text{Dir}(\theta|\alpha + \eta) \propto \prod_k \theta_k^{N_k + \alpha_k - 1} \quad \text{again, we add the real counts to pseudo-counts}$$

$$\text{posterior predictive} \quad p(x = k|\mathcal{D}) = \frac{\alpha_k + N_k}{\sum_{k'} \alpha_{k'} + N_{k'}}$$

$$\text{MAP} \quad \theta_k^{MAP} = \frac{\alpha_k + N_k - 1}{(\sum_{k'} \alpha_{k'} + N_{k'}) - K}$$

# Summary

in ML we often build a probabilistic model of the data  $p(x; \theta)$

learning a good model could mean **maximizing the likelihood** of the data

$$\max_{\theta} \log p(\mathcal{D}|\theta) \quad \left| \begin{array}{l} \text{sometimes closed form solution} \\ \text{for more complex } p, \text{ we use numerical methods} \end{array} \right.$$

an alternative is a **Bayesian approach**:

- maintain a **distribution** over model parameters
- can specify our **prior** knowledge  $p(\theta)$
- we can use **Bayes rule** to update our belief after new observation  $p(\theta|\mathcal{D})$
- we can make predictions using **posterior predictive**  $p(x|\mathcal{D})$
- can be computationally **expensive** (*not in our examples so far*)

a middle path is **MAP estimate**:  $\max_{\theta} \log p(\mathcal{D}|\theta)p(\theta)$

- models our **prior** belief
- use a single point estimate and picks the model with highest posterior probability