COMP 551 - Applied Machine Learning A Brief Tutorial on Probability Theory

Safa Alver (slides adapted from Stanford's CS229 Probability Theory Review)

McGill University

January 16, 2021

> This is not an comprehensive review of Probability Theory.

- ▶ This is not an comprehensive review of Probability Theory.
- ▶ The focus is on the subset related to COMP 551.

- ▶ This is not an comprehensive review of Probability Theory.
- ▶ The focus is on the subset related to COMP 551.
- More references can be found at the end of the slides.

- This is not an comprehensive review of Probability Theory.
- ▶ The focus is on the subset related to COMP 551.
- More references can be found at the end of the slides.
- Also please shoot me an email if you find any typos or mistakes!

Outline

Probability Theory Elements of Probability Theory Random Variables Two Random Variables Multiple Random Variables

Outline

Probability Theory Elements of Probability Theory

Random Variables Two Random Variables Multiple Random Variables Why Probability Theory?

▶ There are lots of uncertainty in the world.

Why Probability Theory?

- ▶ There are lots of uncertainty in the world.
- Probability theory provides a consistent framework for quantification and manipulation of uncertainty.

Sample space, denoted as Ω, is the set of all possible outcomes of an experiment.

- Sample space, denoted as Ω, is the set of all possible outcomes of an experiment.
- Observations, denoted as ω ∈ Ω, are points in the sample space. They are also called sampled outcomes.

- Sample space, denoted as Ω, is the set of all possible outcomes of an experiment.
- Observations, denoted as ω ∈ Ω, are points in the sample space. They are also called sampled outcomes.
- ► Events, denoted as A ∈ Ω, are subsets of the sample space. Note that a set of events is also an event.

- Sample space, denoted as Ω, is the set of all possible outcomes of an experiment.
- Observations, denoted as ω ∈ Ω, are points in the sample space. They are also called sampled outcomes.
- ► Events, denoted as A ∈ Ω, are subsets of the sample space. Note that a set of events is also an event.
- Example: Consider the experiment of flipping a coin twice:
 - $\blacktriangleright \ \Omega = \{HH, HT, TH, TT\}.$
 - The sampled outcomes can be $\omega = HH$ or $\omega = HT$.
 - One possible event is A = {HH, TT}, which corresponds to the event of both flips being the same.

Axioms of Probability Theory

A probability measure is a function that maps events to the interval [0, 1], i.e. P : A → [0, 1].

Axioms of Probability Theory

- A probability measure is a function that maps events to the interval [0, 1], i.e. P : A → [0, 1].
- The probability measure satisfies the following properties:

1.
$$P(A) \ge 0$$
 for all A.

2.
$$P(\Omega) = 1$$
.

3. If A_1, A_2, \ldots are disjoint events $(A_i \cap A_j = \emptyset)$, then

$$P\left(\bigcup_{i}A_{i}\right)=\sum_{i}P(A_{i}).$$

These three properties are called the **axioms of probability theory**.

Properties of the Probability Measure

Properties:

- If $A \subseteq B$, then $P(A) \leq P(B)$.
- ▶ $P(A \cap B) \leq \min(P(A), P(B)).$

Union Bound:

$$P(A \cup B) \leq P(A) + P(B)$$

• Law of Total Probability: If A_1, \ldots, A_k are disjoint events such that $\bigcup_{i=1}^k A_i = \Omega$, then

$$\sum_{i=1}^k P(A_i) = 1.$$

► For more see page 1 of CS229's Probability Theory Review.

Joint and Conditional Probabilities

▶ **Joint probability** of events *A* and *B*, denoted as *P*(*A*, *B*), is the probability that both events will occur

 $P(A,B)=P(A\cap B).$

Joint and Conditional Probabilities

▶ Joint probability of events A and B, denoted as P(A, B), is the probability that both events will occur

 $P(A,B)=P(A\cap B).$

- Conditional probability of A given B, denoted as P(A|B), is the probability that A will occur given B has already occurred.
 - Assuming P(B) > 0, it is defined as

$$P(A|B) = \frac{P(A,B)}{P(B)}.$$

Joint and Conditional Probabilities

▶ Joint probability of events A and B, denoted as P(A, B), is the probability that both events will occur

 $P(A,B)=P(A\cap B).$

- Conditional probability of A given B, denoted as P(A|B), is the probability that A will occur given B has already occurred.
 - Assuming P(B) > 0, it is defined as

$$P(A|B) = \frac{P(A,B)}{P(B)}.$$

This leads to the product rule in probability theory:

$$P(A,B) = P(A|B)P(B) = P(B|A)P(A).$$

Independence

Events A and B are independent if and only if

P(A,B)=P(A)P(B),

or equivalently (using the product rule),

$$P(A|B) = P(A).$$

Intuitively, this says that observing B does not have any effect on the probability of A.

Independence

Events A and B are **independent** if and only if

P(A,B)=P(A)P(B),

or equivalently (using the product rule),

$$P(A|B) = P(A).$$

Intuitively, this says that observing B does not have any effect on the probability of A.

Also events A and B are conditionally independent given event C if and only if

$$P(A, B|C) = P(A|C)P(B|C).$$

Outline

Probability Theory

Elements of Probability Theory

Random Variables

Two Random Variables Multiple Random Variables

Sample space is composed of events as five consequent coin tosses.

- Sample space is composed of events as five consequent coin tosses.
- But how do we go from these events to numerical outcomes that we actually care about? For example the number of heads?

- Sample space is composed of events as five consequent coin tosses.
- But how do we go from these events to numerical outcomes that we actually care about? For example the number of heads?
- A random variable is a mapping X : Ω → ℝ which assigns a real number X(ω) to each observed outcome ω ∈ Ω in the sample space.

- Sample space is composed of events as five consequent coin tosses.
- But how do we go from these events to numerical outcomes that we actually care about? For example the number of heads?
- A random variable is a mapping X : Ω → ℝ which assigns a real number X(ω) to each observed outcome ω ∈ Ω in the sample space.
- While the random variable is denoted with upper case letters X(ω) (or simply X), the values it can take are denoted with lower case ones x.

- Sample space is composed of events as five consequent coin tosses.
- But how do we go from these events to numerical outcomes that we actually care about? For example the number of heads?
- A random variable is a mapping X : Ω → ℝ which assigns a real number X(ω) to each observed outcome ω ∈ Ω in the sample space.
- While the random variable is denoted with upper case letters X(ω) (or simply X), the values it can take are denoted with lower case ones x.
- Example: Consider the experiment of flipping a coin 5 times. $X(\omega)$ can be a counter that counts the number of heads. In this case if the outcome is $\omega_0 = HTTTH$, then $X(\omega_0) = 2$.

Discrete and Continuous Random Variables

Discrete random variables

- Can take only a finite number of values
- Example: Number of heads in the sequence of 5 coin tosses
- Here, the probability of the set associated with a random variable X taking on some specific value k is:

$$P(X = k) = P(\{\omega : X(\omega) = k\}).$$

Discrete and Continuous Random Variables

Discrete random variables

- Can take only a finite number of values
- Example: Number of heads in the sequence of 5 coin tosses
- Here, the probability of the set associated with a random variable X taking on some specific value k is:

$$P(X = k) = P(\{\omega : X(\omega) = k\}).$$

Continuous random variables

- Can take on a infinite number of possible values
- Example: Time of bus arrivals in a bus station
- Here, the probability of the set associated with a random variable X taking on some specific value between a and b (a < b) is:</p>

$$P(a \le X \le b) = P(\{\omega : a \le X(\omega) \le b\}).$$

When X is discrete random variable, we use probability mass functions to assign probabilities to random variables taking certain values.

- When X is discrete random variable, we use probability mass functions to assign probabilities to random variables taking certain values.
- ▶ The probability mass function (PMF) is a function $p_X : \mathbb{R} \to [0, 1]$ such that

$$p_X(x)=P(X=x).$$

- When X is discrete random variable, we use probability mass functions to assign probabilities to random variables taking certain values.
- ▶ The probability mass function (PMF) is a function $p_X : \mathbb{R} \to [0, 1]$ such that

$$p_X(x) = P(X = x).$$

Intuitively, it is the probability that the random variable X(ω) will take the value x.

Example: If X(ω) is a random variable indicating the number of H occurrences in 2 coin tosses, we have

$$p_X(2) = P(X = 2) = \frac{1}{4},$$

 $p_X(1) = P(X = 1) = \frac{1}{2},$
 $p_X(0) = P(X = 0) = \frac{1}{4}.$

Example: If X(ω) is a random variable indicating the number of H occurrences in 2 coin tosses, we have

$$p_X(2) = P(X = 2) = \frac{1}{4},$$

 $p_X(1) = P(X = 1) = \frac{1}{2},$
 $p_X(0) = P(X = 0) = \frac{1}{4}.$

For the properties PMFs see page 3 of CS229's Probability Theory Review.

Probability Density Functions

When X is continuous random variable, we use probability density functions to assign probabilities to random variables taking certain values in a specific interval.

Probability Density Functions

- When X is continuous random variable, we use probability density functions to assign probabilities to random variables taking certain values in a specific interval.
- The probability density function (PDF) is a function $f_X : \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} f_X(x) dx = P(x \le X \le x + \Delta x).$$

Probability Density Functions

- When X is continuous random variable, we use probability density functions to assign probabilities to random variables taking certain values in a specific interval.
- The probability density function (PDF) is a function $f_X : \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} f_X(x) dx = P(x \le X \le x + \Delta x).$$

It is important to note that f_X(x) is not equal to P(X = x), i.e.

$$f_X(x) \neq P(X = x).$$

It is its integral over an interval that gives the probability.

Probability Density Functions

- When X is continuous random variable, we use probability density functions to assign probabilities to random variables taking certain values in a specific interval.
- The probability density function (PDF) is a function $f_X : \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} f_X(x) dx = P(x \le X \le x + \Delta x).$$

It is important to note that f_X(x) is not equal to P(X = x), i.e.

$$f_X(x) \neq P(X = x).$$

It is its integral over an interval that gives the probability.

In fact, f_X(x) can even be greater than 1 for certain x values. However, it cannot be negative.

Probability Density Functions

- When X is continuous random variable, we use probability density functions to assign probabilities to random variables taking certain values in a specific interval.
- The probability density function (PDF) is a function $f_X : \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} f_X(x) dx = P(x \le X \le x + \Delta x).$$

It is important to note that f_X(x) is not equal to P(X = x), i.e.

$$f_X(x) \neq P(X = x).$$

It is its integral over an interval that gives the probability.

- In fact, f_X(x) can even be greater than 1 for certain x values. However, it cannot be negative.
- For the properties PDFs see page 4 of CS229's Probability Theory Review.

► The expectation (expected value or mean) of a

discrete random variable X is defined as:

$$\mathbb{E}[X] = \sum_{x \in Val(X)} x p_X(x),$$

The expectation (expected value or mean) of a

discrete random variable X is defined as:

$$\mathbb{E}[X] = \sum_{x \in Val(X)} x p_X(x),$$

continuous random variable Y defined as:

$$\mathbb{E}[Y] = \int_{-\infty}^{\infty} y f_Y(y) dy.$$

The expectation (expected value or mean) of a

discrete random variable X is defined as:

$$\mathbb{E}[X] = \sum_{x \in Val(X)} x p_X(x),$$

continuous random variable Y defined as:

$$\mathbb{E}[Y] = \int_{-\infty}^{\infty} y f_Y(y) dy.$$

Intuitively, the expectation of random variable can be thought of as a "weighted average" of the values it can take, where the weights are p_X(x) or f_Y(y).

The expectation (expected value or mean) of a

discrete random variable X is defined as:

$$\mathbb{E}[X] = \sum_{x \in Val(X)} x p_X(x),$$

continuous random variable Y defined as:

$$\mathbb{E}[Y] = \int_{-\infty}^{\infty} y f_Y(y) dy.$$

- Intuitively, the expectation of random variable can be thought of as a "weighted average" of the values it can take, where the weights are p_X(x) or f_Y(y).
- For the properties expectations see page 4 of CS229's Probability Theory Review.

The variance of a (discrete or continuous) random variable is defined as:

$$\mathsf{Var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

The variance of a (discrete or continuous) random variable is defined as:

$$\operatorname{Var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

With several steps of derivation, it can also be written as

$$\operatorname{Var}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2.$$

The variance of a (discrete or continuous) random variable is defined as:

$$\operatorname{Var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

With several steps of derivation, it can also be written as

$$\operatorname{Var}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2.$$

Intuitively, it is a measure of how concentrated the distribution of a random variables is around its mean.

The variance of a (discrete or continuous) random variable is defined as:

$$\operatorname{Var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

With several steps of derivation, it can also be written as

$$\operatorname{Var}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2.$$

- Intuitively, it is a measure of how concentrated the distribution of a random variables is around its mean.
- For the properties variance see page 4 of CS229's Probability Theory Review.

Common Random Variables

Below are the distributions, means and variances of some common random variables¹:

Distribution	PDF or PMF	Mean	Variance
Bernoulli(p)	$\left\{\begin{array}{ll} p, & \text{if } x = 1\\ 1-p, & \text{if } x = 0. \end{array}\right.$	p	p(1-p)
Binomial(n, p)	$\binom{n}{k} p^k (1-p)^{n-k}$ for $0 \le k \le n$	np	npq
Geometric(p)	$p(1-p)^{k-1}$ for $k = 1, 2,$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
$Poisson(\lambda)$	$e^{-\lambda}\lambda^x/x!$ for $k=1,2,\ldots$	$\overline{\lambda}$	$\overline{\lambda}$
Uniform(a, b)	$\frac{1}{b-a} \forall x \in (a,b)$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Gaussian(μ, σ^2)	$\frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	μ	σ^2
$Exponential(\lambda)$	$\lambda e^{-\lambda x} \ x \ge 0, \lambda > 0$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$

¹Taken from CS229's Probability Theory Review.

Common Random Variables

Below are the distributions, means and variances of some common random variables¹:

Distribution	PDF or PMF	Mean	Variance
Bernoulli(p)	$\left\{\begin{array}{ll} p, & \text{if } x = 1\\ 1-p, & \text{if } x = 0. \end{array}\right.$	p	p(1-p)
Binomial(n, p)	$\binom{n}{k} p^k (1-p)^{n-k}$ for $0 \le k \le n$	np	npq
Geometric(p)	$p(1-p)^{k-1}$ for $k = 1, 2,$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
$Poisson(\lambda)$	$e^{-\lambda}\lambda^x/x!$ for $k=1,2,\ldots$	λ	$\overline{\lambda}$
Uniform(a, b)	$\frac{1}{b-a} \forall x \in (a,b)$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Gaussian(μ, σ^2)	$\frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	μ	σ^2
$Exponential(\lambda)$	$\lambda e^{-\lambda x} \ x \ge 0, \lambda > 0$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$

Do not try to memorize them, they are put here for reference.

¹Taken from CS229's Probability Theory Review.

Gaussian Distribution

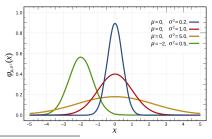
Among these distributions the Gaussian distribution (also known as the Normal distribution) is particularly important as it shows up everywhere.

Gaussian Distribution

- Among these distributions the Gaussian distribution (also known as the Normal distribution) is particularly important as it shows up everywhere.
- It has the following PDF:

$$p_X(x) = \mathcal{N}(x|\mu,\sigma) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-\mu)^2}{2\sigma^2}},$$

and the following shape²:



²Taken from Wikipedia.

Outline

Probability Theory

Elements of Probability Theory Random Variables

Two Random Variables

Multiple Random Variables

Two Random Variables

Thus far, we have considered single random variables. In many situations, however, there may be more than one quantity that we are interested in knowing during a random experiment.

Two Random Variables

- Thus far, we have considered single random variables. In many situations, however, there may be more than one quantity that we are interested in knowing during a random experiment.
- For instance, in an experiment where we flip a coin ten times, we may care about both X(ω) = "the number of heads that come up" as well as Y(ω) = "the length of the longest run of consecutive heads".

Two Random Variables

- Thus far, we have considered single random variables. In many situations, however, there may be more than one quantity that we are interested in knowing during a random experiment.
- For instance, in an experiment where we flip a coin ten times, we may care about both X(ω) = "the number of heads that come up" as well as Y(ω) = "the length of the longest run of consecutive heads".
- In this part, we consider the setting of two random variables.

When X and Y are discrete random variables, we use joint PMFs to assign probabilities to random variables taking certain values.

- When X and Y are discrete random variables, we use joint PMFs to assign probabilities to random variables taking certain values.
- ▶ The joint **PMF** is a function $p_{XY} : \mathbb{R} \times \mathbb{R} \rightarrow [0, 1]$ such that

$$p_{XY}(x,y) = P(X = x, Y = y).$$

- When X and Y are discrete random variables, we use joint PMFs to assign probabilities to random variables taking certain values.
- ▶ The joint **PMF** is a function $p_{XY} : \mathbb{R} \times \mathbb{R} \rightarrow [0, 1]$ such that

$$p_{XY}(x,y) = P(X = x, Y = y).$$

Intuitively, it is the probability that the random variables X(ω) and Y(ω) will take the values x and y.

Joint and Marginal Probability Mass Functions...

How does the joint PMF relate to PMFs for each variable separately? It turns out that

$$p_X(x) = \sum_{y} p_{XY}(x, y), \quad p_Y(y) = \sum_{x} p_{XY}(x, y).$$

Joint and Marginal Probability Mass Functions...

How does the joint PMF relate to PMFs for each variable separately? It turns out that

$$p_X(x) = \sum_y p_{XY}(x,y), \quad p_Y(y) = \sum_x p_{XY}(x,y).$$

p_X(x) and p_Y(y) are referred to marginal PMFs of X and Y, respectively.

Joint and Marginal Probability Mass Functions...

How does the joint PMF relate to PMFs for each variable separately? It turns out that

$$p_X(x) = \sum_{y} p_{XY}(x, y), \quad p_Y(y) = \sum_{x} p_{XY}(x, y).$$

- p_X(x) and p_Y(y) are referred to marginal PMFs of X and Y, respectively.
- This summation is referred to as marginalization.

When X and Y are continuous random variables, we use probability density functions to assign probabilities to random variables taking certain values in specific intervals.

- When X and Y are continuous random variables, we use probability density functions to assign probabilities to random variables taking certain values in specific intervals.
- The **joint PDF** is a function $f_{XY} : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} \int_{y}^{y+\Delta y} f_{XY}(x,y) dx dy$$

= $P(x \le X \le x + \Delta x, y \le Y \le y + \Delta y).$

- When X and Y are continuous random variables, we use probability density functions to assign probabilities to random variables taking certain values in specific intervals.
- The **joint PDF** is a function $f_{XY} : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} \int_{y}^{y+\Delta y} f_{XY}(x, y) dx dy$$

= $P(x \le X \le x + \Delta x, y \le Y \le y + \Delta y).$

It is important to note again that

$$f_{XY}(x,y) \neq P(X=x,Y=y).$$

It is its integral over the intervals that gives the probability.

- When X and Y are continuous random variables, we use probability density functions to assign probabilities to random variables taking certain values in specific intervals.
- The **joint PDF** is a function $f_{XY} : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ such that

$$\int_{x}^{x+\Delta x} \int_{y}^{y+\Delta y} f_{XY}(x, y) dx dy$$

= $P(x \le X \le x + \Delta x, y \le Y \le y + \Delta y).$

It is important to note again that

$$f_{XY}(x,y) \neq P(X=x,Y=y).$$

It is its integral over the intervals that gives the probability.

In fact, f_{XY}(x, y) can even be greater than 1 for certain x and y values. However, it cannot be negative.

Analogous to the discrete case we have:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x,y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{XY}(x,y) dx.$$

Analogous to the discrete case we have:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x,y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{XY}(x,y) dx.$$

► f_X(x) and f_Y(y) are referred to marginal PDFs of X and Y, respectively.

Conditional Distributions

In the discrete case, the conditional PMF of Y given X is defined as:

$$p_{Y|X}(y|x) = \frac{p_{XY}(x,y)}{p_X(x)},$$

assuming that $p_X(x) > 0$.

In the discrete case, the conditional PMF of Y given X is defined as:

$$p_{Y|X}(y|x) = \frac{p_{XY}(x,y)}{p_X(x)},$$

assuming that $p_X(x) > 0$.

For the continuous case see page 8 of CS229's Probability Theory Review, but it has the same form.

Bayes' Rule

A useful formula that often arises when trying to derive an expression for the conditional probability of one event given the other is **Bayes' Rule**.

Bayes' Rule

- A useful formula that often arises when trying to derive an expression for the conditional probability of one event given the other is **Bayes' Rule**.
- ▶ In the case of discrete random variables X and Y:

$$p_{Y|X}(y|x) = \frac{p_{X|Y}(x|y)p_Y(y)}{p_X(x)}$$

Posterior =
$$\frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}$$

(Posterior \prior).

Bayes' Rule

- A useful formula that often arises when trying to derive an expression for the conditional probability of one event given the other is **Bayes' Rule**.
- ▶ In the case of discrete random variables X and Y:

$$p_{Y|X}(y|x) = \frac{p_{X|Y}(x|y)p_Y(y)}{p_X(x)}$$

Posterior =
$$\frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}$$

(Posterior \propto Likelihood \times Prior).

The same thing can be done with PDFs in the case of continuous random variables.

Independence

▶ Two discrete random variables X and Y are independent if

$$p_{XY}(x,y) = p_X(x)p_Y(y),$$

for all $x \in Val(X)$ and $y \in Val(Y)$.

Independence

Two discrete random variables X and Y are independent if

$$p_{XY}(x,y) = p_X(x)p_Y(y),$$

for all $x \in Val(X)$ and $y \in Val(Y)$.

For the continuous case see page 8 of CS229's Probability Theory Review, but it has the same form.

Independence

Two discrete random variables X and Y are independent if

$$p_{XY}(x,y) = p_X(x)p_Y(y),$$

for all $x \in Val(X)$ and $y \in Val(Y)$.

- For the continuous case see page 8 of CS229's Probability Theory Review, but it has the same form.
- Intuitively, two random variables are independent if knowing the value of one variable will never affect the probability of knowing the other.

Suppose that we have two discrete random variables X and Y, and g(.,.) is a function of these two random variables.

- Suppose that we have two discrete random variables X and Y, and g(.,.) is a function of these two random variables.
- ▶ Then the expected value of g is defined in the following way:

$$\mathbb{E}[g(X,Y)] = \sum_{x \in Val(X)} \sum_{y \in Val(Y)} g(x,y) p_{XY}(x,y).$$

- Suppose that we have two discrete random variables X and Y, and g(.,.) is a function of these two random variables.
- ▶ Then the expected value of g is defined in the following way:

$$\mathbb{E}[g(X,Y)] = \sum_{x \in Val(X)} \sum_{y \in Val(Y)} g(x,y) p_{XY}(x,y).$$

For continuous random variables X and Y the analogous expression is:

$$\mathbb{E}[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{XY}(x,y) dx dy.$$

Using the expectation definition in the previous slide, the covariance of two random variables X and Y is defined as:

$$Cov[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

Using the expectation definition in the previous slide, the covariance of two random variables X and Y is defined as:

$$Cov[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

With a few steps of derivation it can also be written as:

$$Cov[X, Y] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

Using the expectation definition in the previous slide, the covariance of two random variables X and Y is defined as:

$$Cov[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

With a few steps of derivation it can also be written as:

$$Cov[X, Y] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

• When Cov[X, Y] = 0, we say that X and Y are **uncorrelated**.

Using the expectation definition in the previous slide, the covariance of two random variables X and Y is defined as:

$$Cov[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

With a few steps of derivation it can also be written as:

$$Cov[X, Y] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

• When Cov[X, Y] = 0, we say that X and Y are **uncorrelated**.

When X and Y are independent, then Cov[X, Y] = 0. However, the opposite is not always true.

Using the expectation definition in the previous slide, the covariance of two random variables X and Y is defined as:

$$Cov[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

With a few steps of derivation it can also be written as:

$$Cov[X, Y] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

• When Cov[X, Y] = 0, we say that X and Y are **uncorrelated**.

- When X and Y are independent, then Cov[X, Y] = 0. However, the opposite is not always true.
- For the properties covariance see page 9 of CS229's Probability Theory Review.

Outline

Probability Theory

Elements of Probability Theory Random Variables Two Random Variables Multiple Random Variables

Multiple Random Variables

The notions and ideas introduced in the previous section can be generalized to more than two random variables.

Multiple Random Variables

- The notions and ideas introduced in the previous section can be generalized to more than two random variables.
- In particular, suppose that we have n random variables

$$X_1(\omega), X_2(\omega), \ldots, X_n(\omega).$$

Example of Generalization

In the case of having two discrete random variables X and Y, the joint PMF was defined as:

$$p_{XY}(x, y) = P(X = x, Y = y),$$

and marginalization was done as follows:

$$p_X(x) = \sum_{y} p_{XY}(x, y), \quad p_Y(y) = \sum_{x} p_{XY}(x, y).$$

Example of Generalization

In the case of having two discrete random variables X and Y, the joint PMF was defined as:

$$p_{XY}(x, y) = P(X = x, Y = y),$$

and marginalization was done as follows:

$$p_X(x) = \sum_{y} p_{XY}(x, y), \quad p_Y(y) = \sum_{x} p_{XY}(x, y).$$

In the case of having n discrete random variables X₁, X₂,..., X_n, the joint PMF becomes:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = P(X_1 = x_1, X_2 = x_2, ..., X_n = x_n),$$

and marginalization becomes:

$$p_{X_1}(x_1) = \sum_{x_2, x_3, \dots, x_n} p_{X_2 \dots X_n}(x_2, \dots, x_n).$$

Example of Generalization

In the case of having two discrete random variables X and Y, the joint PMF was defined as:

$$p_{XY}(x, y) = P(X = x, Y = y),$$

and marginalization was done as follows:

$$p_X(x) = \sum_{y} p_{XY}(x, y), \quad p_Y(y) = \sum_{x} p_{XY}(x, y).$$

In the case of having n discrete random variables X₁, X₂,..., X_n, the joint PMF becomes:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = P(X_1 = x_1, X_2 = x_2, ..., X_n = x_n),$$

and marginalization becomes:

$$p_{X_1}(x_1) = \sum_{x_2, x_3, \dots, x_n} p_{X_2 \dots X_n}(x_2, \dots, x_n).$$

Note that the same can be done for x_2, \ldots, x_n .

Chain Rule and Mutual Independence

From the definition of conditional probabilities, one can show that:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = p_{X_1}(x_1) \prod_{i=2}^n p_{X_i}(x_i|x_1, ..., x_{i-1}).$$

This is called the **chain rule** in probability theory.

Chain Rule and Mutual Independence

From the definition of conditional probabilities, one can show that:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = p_{X_1}(x_1) \prod_{i=2}^n p_{X_i}(x_i|x_1, ..., x_{i-1}).$$

This is called the **chain rule** in probability theory.

In this way, a joint probability is written in terms of conditional probabilities.

Chain Rule and Mutual Independence

From the definition of conditional probabilities, one can show that:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = p_{X_1}(x_1) \prod_{i=2}^n p_{X_i}(x_i|x_1, ..., x_{i-1}).$$

This is called the **chain rule** in probability theory.

- In this way, a joint probability is written in terms of conditional probabilities.
- We say that X_1, X_2, \ldots, X_n are **mutually independent** if:

$$p_{X_1X_2...X_n}(x_1, x_2, ..., x_n) = \prod_{i=1}^n p_{X_i}(x_i).$$

Independent and Identically Distributed (IID)

A set of random variables are independent and identically distributed (i.i.d.) if

they are sampled from the same distribution

and are mutually independent.

Independent and Identically Distributed (IID)

A set of random variables are independent and identically distributed (i.i.d.) if

they are sampled from the same distribution

and are mutually independent.

Example: Consecutive coin flips are assumed to be i.i.d.:

- ▶ The probability of *H* is the same for each flip.
- One flip's outcome doesn't affect the others.

Random Vectors

When working with multiple random variables X₁, X₂,..., X_n, it is often convenient to put them in a vector:

$$\boldsymbol{X} = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}.$$

This resulting vector is called a **random vector** (a mapping $\boldsymbol{X} : \Omega \to \mathbb{R}^n$).

Random Vectors

When working with multiple random variables X₁, X₂,..., X_n, it is often convenient to put them in a vector:

$$\boldsymbol{X} = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$$

This resulting vector is called a **random vector** (a mapping $\boldsymbol{X} : \Omega \to \mathbb{R}^n$).

It should be noted that this is just another notation, and nothing more.

Covariance Matrix

For a given random vector X, its covariance matrix Σ is an n × n square matrix and is defined as:

$$\boldsymbol{\Sigma} = \mathbb{E}[(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])^{\top}].$$

And its (i, j)th entry is

$$\Sigma_{ij} = Cov[X_i, X_j].$$

Covariance Matrix

For a given random vector X, its covariance matrix Σ is an n × n square matrix and is defined as:

$$\boldsymbol{\Sigma} = \mathbb{E}[(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])^{\top}].$$

And its (i, j)th entry is

$$\Sigma_{ij} = Cov[X_i, X_j].$$

With a few steps of derivation it can also be written as:

$$\boldsymbol{\Sigma} = \mathbb{E}[\boldsymbol{X}\boldsymbol{X}^{\top}] - \mathbb{E}[\boldsymbol{X}]\mathbb{E}[\boldsymbol{X}]^{\top}.$$

Covariance Matrix

For a given random vector X, its covariance matrix Σ is an n × n square matrix and is defined as:

$$\boldsymbol{\Sigma} = \mathbb{E}[(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])(\boldsymbol{X} - \mathbb{E}[\boldsymbol{X}])^{\top}].$$

And its (i, j)th entry is

$$\Sigma_{ij} = Cov[X_i, X_j].$$

With a few steps of derivation it can also be written as:

$$\boldsymbol{\Sigma} = \mathbb{E}[\boldsymbol{X}\boldsymbol{X}^{\top}] - \mathbb{E}[\boldsymbol{X}]\mathbb{E}[\boldsymbol{X}]^{\top}.$$

It should be noted that Σ is positive semidefinite and symmetric.

Multivariate Gaussian Distribution

A particularly important example of a probability distribution over random vectors is the multivariate Gaussian (normal) distribution.

Multivariate Gaussian Distribution

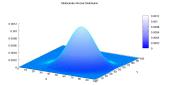
- A particularly important example of a probability distribution over random vectors is the multivariate Gaussian (normal) distribution.
- It is a generalization of the univariate Guassian to higher dimensions.

Multivariate Gaussian Distribution

- A particularly important example of a probability distribution over random vectors is the multivariate Gaussian (normal) distribution.
- It is a generalization of the univariate Guassian to higher dimensions.
- ▶ A multivariate Gaussian distribution with mean $\mu \in \mathbb{R}^n$ and covariance $\Sigma \in \mathbb{R}^{n \times n}$ has the following PDF:

$$p_{\boldsymbol{X}}(\boldsymbol{x}) = \mathcal{N}(\boldsymbol{x}|\boldsymbol{\mu},\boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{\frac{n}{2}}|\boldsymbol{\Sigma}|^{\frac{1}{2}}} e^{-\frac{(\boldsymbol{x}-\boldsymbol{\mu})^{\top}\boldsymbol{\Sigma}^{-1}(\boldsymbol{x}-\boldsymbol{\mu})}{2}},$$

and the following shape 3 (in 2D):



³Taken from Wikipedia.

References

This tutorial is mainly adapted from Stanford's CS229 Probability Theory Review. However, it doesn't give all the details. For the details please refer to this source.